

COMP2310/COMP6310

Systems, Networks, & Concurrency

Convenor: Prof John Taylor

Course Update

- **Assignment 1 – Marking now**
- **Checkpoint 2 – Now moved to next week**
 - Attend the lab as per Checkpoint 1
- **Final Exam – Closed Book**
 - Wednesday 12/11/2025 2-5:15pm
 - Melville Hall

Synchronization: Basics

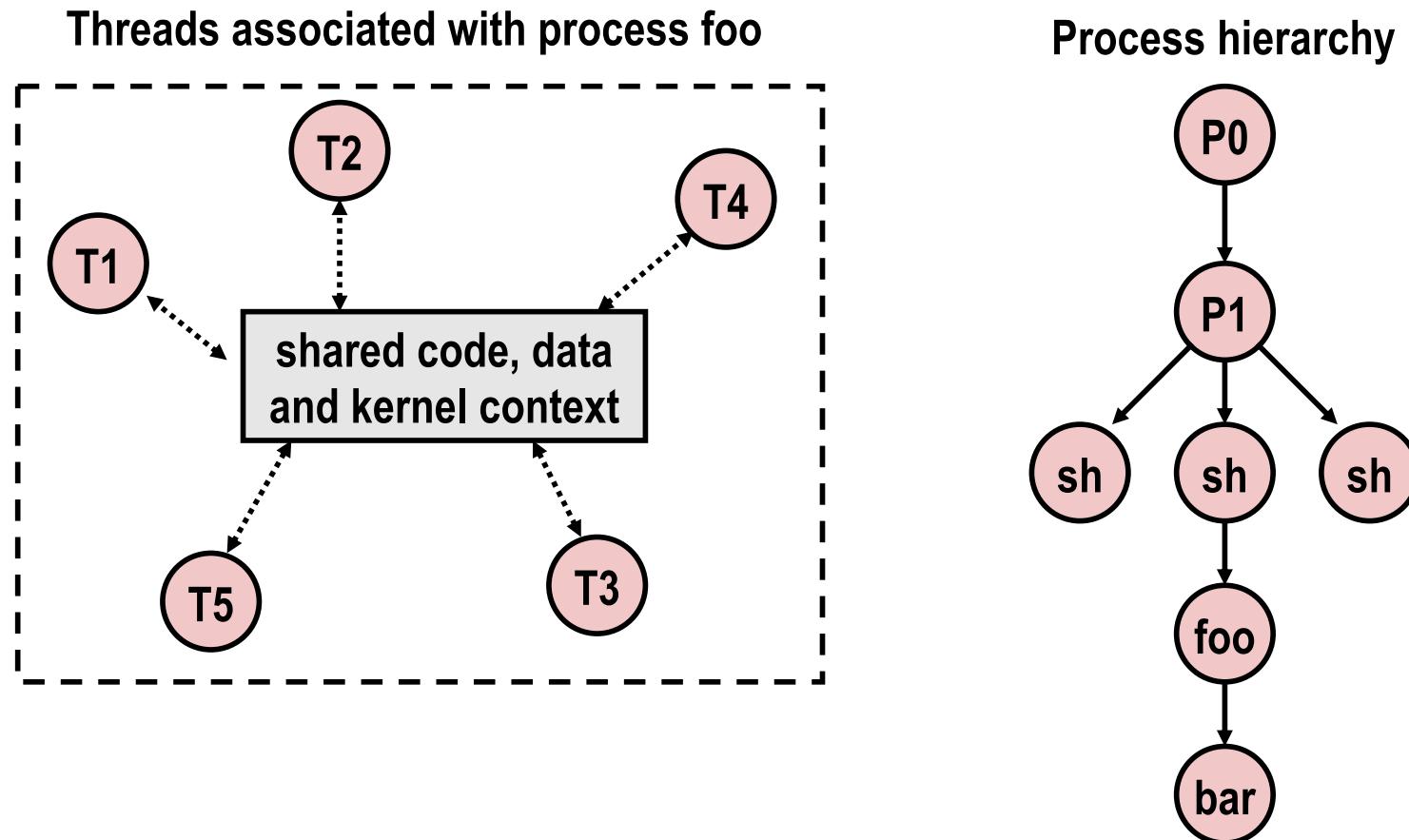
Acknowledgement of material: With changes suited to ANU needs, the slides are obtained from Carnegie Mellon University: <https://www.cs.cmu.edu/~213/>

Shared Variables in Threaded C Programs

- **Question:** Which variables in a threaded C program are shared?
 - The answer is not as simple as “*global variables are shared*” and “*stack variables are private*”
- **Def:** A variable **x** is *shared* if and only if multiple threads reference some instance of **x**.
- **Requires answers to the following questions:**
 - What is the memory model for threads?
 - How are instances of variables mapped to memory?
 - How many threads might reference each of these instances?

Logical View of Threads

- Threads associated with process form a pool of peers
 - Unlike processes which form a tree hierarchy



Threads Memory Model

■ Conceptual model:

- Multiple threads run within the context of a single process
- Each thread has its own separate thread context
 - Thread ID, stack, stack pointer, PC, condition codes, and GP registers
- All threads share the remaining process context
 - Code, data, heap, and shared library segments of the process virtual address space
 - Open files and installed handlers

■ Operationally, this model is not strictly enforced:

- Register values are truly separate and protected, but...
- Any thread can read and write the stack of any other thread

*The mismatch between the conceptual and operational model
is a source of confusion and errors*

Example Program to Illustrate Sharing

```
char **ptr; /* global var */  
  
int main()  
{  
    long i;  
    pthread_t tid;  
    char *msgs[2] = {  
        "Hello from foo",  
        "Hello from bar"  
    };  
  
    ptr = msgs;  
    for (i = 0; i < 2; i++)  
        Pthread_create(&tid,  
                       NULL,  
                       thread,  
                       (void *)i);  
    Pthread_exit(NULL);  
}
```

sharing.c

```
void *thread(void *vargp)  
{  
    long myid = (long)vargp;  
    static int cnt = 0;  
  
    printf("[%ld]: %s (cnt=%d)\n",  
           myid, ptr[myid], ++cnt);  
    return NULL;  
}
```

*Peer threads reference main thread's stack
indirectly through global ptr variable*

Mapping Variable Instances to Memory

■ Global variables

- *Def*: Variable declared outside of a function
- **Virtual memory contains exactly one instance of any global variable**

■ Local variables

- *Def*: Variable declared inside function without `static` attribute
- **Each thread stack contains one instance of each local variable**

■ Local static variables

- *Def*: Variable declared inside function with the `static` attribute
- **Virtual memory contains exactly one instance of any local static variable.**

Mapping Variable Instances to Memory

Global var: 1 instance (ptr [data])

```
char **ptr; /* global var */  
  
int main()  
{  
    long i;  
    pthread_t tid;  
    char *msgs[2] = {  
        "Hello from foo",  
        "Hello from bar"  
    };  
  
    ptr = msgs;  
    for (i = 0; i < 2; i++)  
        Pthread_create(&tid,  
                       NULL,  
                       thread,  
                       (void *)i);  
    Pthread_exit(NULL);  
}
```

sharing.c

Local vars: 1 instance (i.m, msgs.m)

Local var: 2 instances (
myid.p0 [peer thread 0's stack],
myid.p1 [peer thread 1's stack]
)

```
void *thread(void *vargp)  
{  
    long myid = (long)vargp;  
    static int cnt = 0;  
  
    printf("[%ld]: %s (cnt=%d)\n",  
           myid, ptr[myid], ++cnt);  
    return NULL;  
}
```

Local static var: 1 instance (cnt [data])

Shared Variable Analysis

■ Which variables are shared?

<i>Variable instance</i>	<i>Referenced by main thread?</i>	<i>Referenced by peer thread 0?</i>	<i>Referenced by peer thread 1?</i>
ptr	yes	yes	yes
cnt	no	yes	yes
i.m	yes	no	no
msgs.m	yes	yes	yes
myid.p0	no	yes	no
myid.p1	no	no	yes

- Answer: A variable **x** is shared iff multiple threads reference at least one instance of **x**. Thus:
 - **ptr, cnt, and msgs** are shared
 - **i and myid** are **not** shared

Synchronizing Threads

- Shared variables are handy...
- ...but introduce the possibility of nasty *synchronization* errors.

badcnt.c: Improper Synchronization

```
/* Global shared variable */
volatile long cnt = 0; /* Counter */

int main(int argc, char **argv)
{
    long niters;
    pthread_t tid1, tid2;

    niters = atoi(argv[1]);
    Pthread_create(&tid1, NULL,
                   thread, &niters);
    Pthread_create(&tid2, NULL,
                   thread, &niters);
    Pthread_join(tid1, NULL);
    Pthread_join(tid2, NULL);

    /* Check result */
    if (cnt != (2 * niters))
        printf("BOOM! cnt=%ld\n", cnt);
    else
        printf("OK cnt=%ld\n", cnt);
    exit(0);
}
```

badcnt.c

```
/* Thread routine */
void *thread(void *vargp)
{
    long i, niters =
        *((long *)vargp);

    for (i = 0; i < niters; i++)
        cnt++;

    return NULL;
}
```

```
linux> ./badcnt 10000
OK cnt=20000
linux> ./badcnt 10000
BOOM! cnt=13051
linux>
```

cnt should equal 20,000.

What went wrong?

Assembly Code for Counter Loop

C code for counter loop in thread i

```
for (i = 0; i < niters; i++)
    cnt++;
```

Asm code for thread i

movq (%rdi), %rcx	H_i : Head
testq %rcx, %rcx	
jle .L2	
movl \$0, %eax	
<hr style="border-top: 1px dashed black;"/>	
.L3:	L_i : Load cnt U_i : Update cnt S_i : Store cnt
movq cnt(%rip), %rdx	
addq \$1, %rdx	
movq %rdx, cnt(%rip)	
<hr style="border-top: 1px dashed black;"/>	
addq \$1, %rax	T_i : Tail
cmpq %rcx, %rax	
jne .L3	
.L2:	

Concurrent Execution

- **Key idea:** In general, any sequentially consistent interleaving is possible, but some give an unexpected result!

- I_i denotes that thread i executes instruction I
- $\%rdx_i$ is the content of $\%rdx$ in thread i 's context

i (thread)	$instr_i$	$\%rdx_1$	$\%rdx_2$	cnt
1	H_1	-	-	0
1	L_1	0	-	0
1	U_1	1	-	0
1	S_1	1	-	1
2	H_2	-	-	1
2	L_2	-	1	1
2	U_2	-	2	1
2	S_2	-	2	2
2	T_2	-	2	2
1	T_1	1	-	2



Thread 1
critical section



Thread 2
critical section

OK

L_i : Load cnt
 U_i : Update cnt
 S_i : Store cnt

Concurrent Execution (cont)

- Incorrect ordering: two threads increment the counter, but the result is 1 instead of 2

i (thread)	$instr_i$	$\%rdx_1$	$\%rdx_2$	cnt
1	H_1	-	-	0
1	L_1	0	-	0
1	U_1	1	-	0
2	H_2	-	-	0
2	L_2	-	0	0
1	S_1	1	-	1
1	T_1	1	-	1
2	U_2	-	1	1
2	S_2	-	1	1
2	T_2	-	1	1



Oops!

L_i : Load cnt
 U_i : Update cnt
 S_i : Store cnt

Concurrent Execution (cont)

- How about this ordering?

i (thread)	instr _i	%rdx ₁	%rdx ₂	cnt
1	H ₁			0
1	L ₁	0		
2	H ₂			
2	L ₂		0	
2	U ₂		1	
2	S ₂		1	1
1	U ₁	1		
1	S ₁	1		1
1	T ₁			1
2	T ₂			1

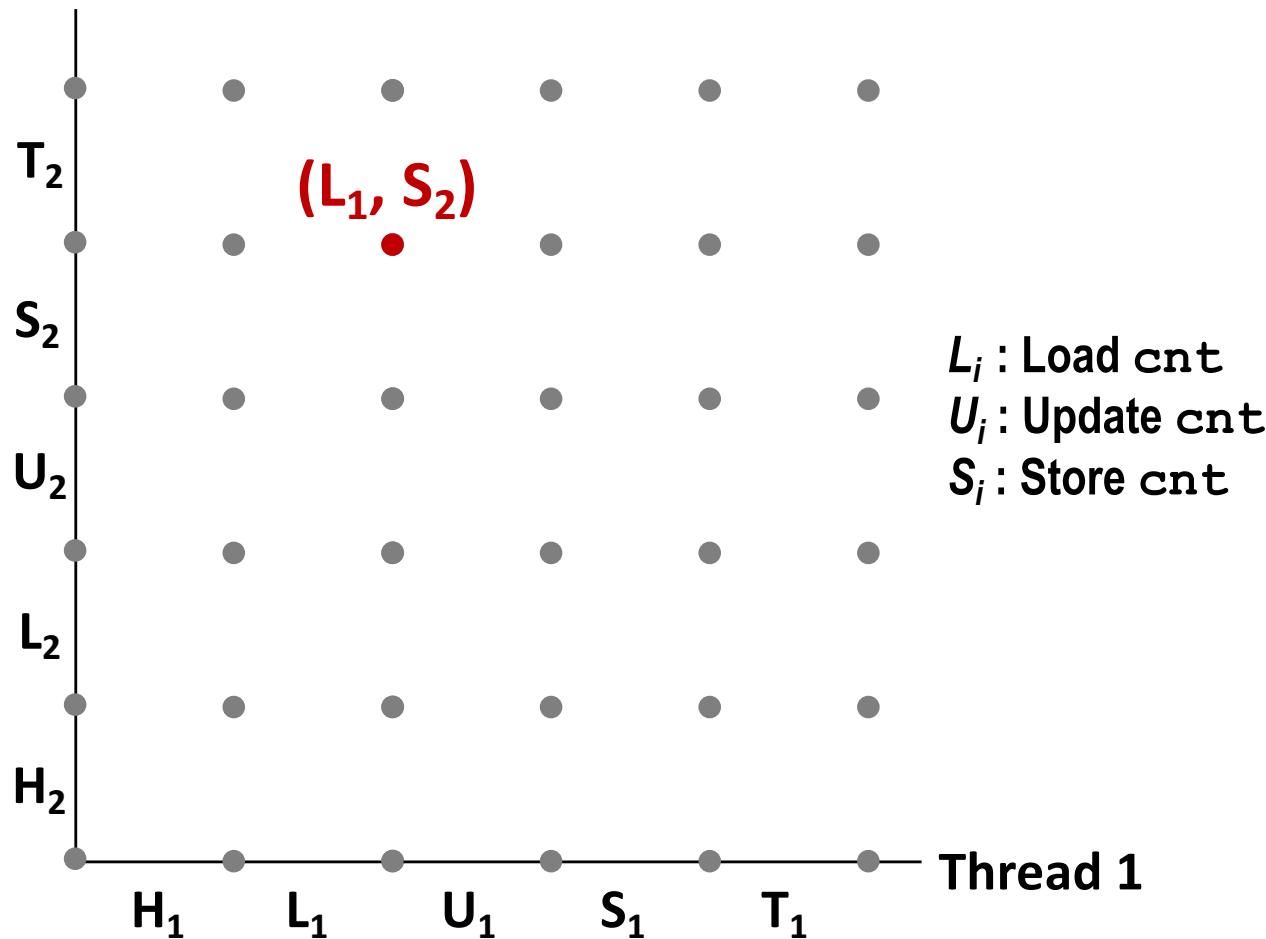


Oops!

- We can analyze the behavior using a *progress graph*

Progress Graphs

Thread 2



A *progress graph* depicts the discrete *execution state space* of concurrent threads.

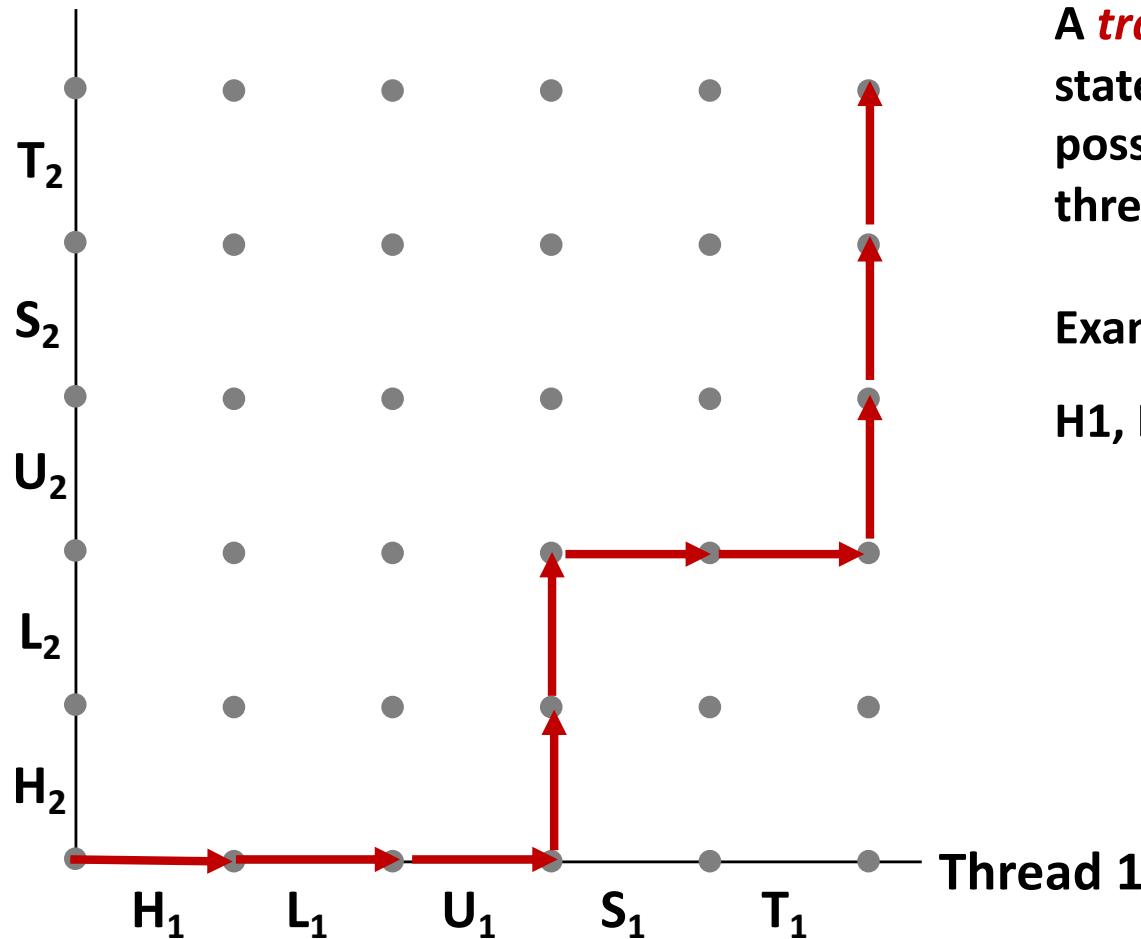
Each axis corresponds to the sequential order of instructions in a thread.

Each point corresponds to a possible *execution state* $(\text{Inst}_1, \text{Inst}_2)$.

E.g., (L_1, S_2) denotes state where thread 1 has completed L_1 and thread 2 has completed S_2 .

Trajectories in Progress Graphs

Thread 2

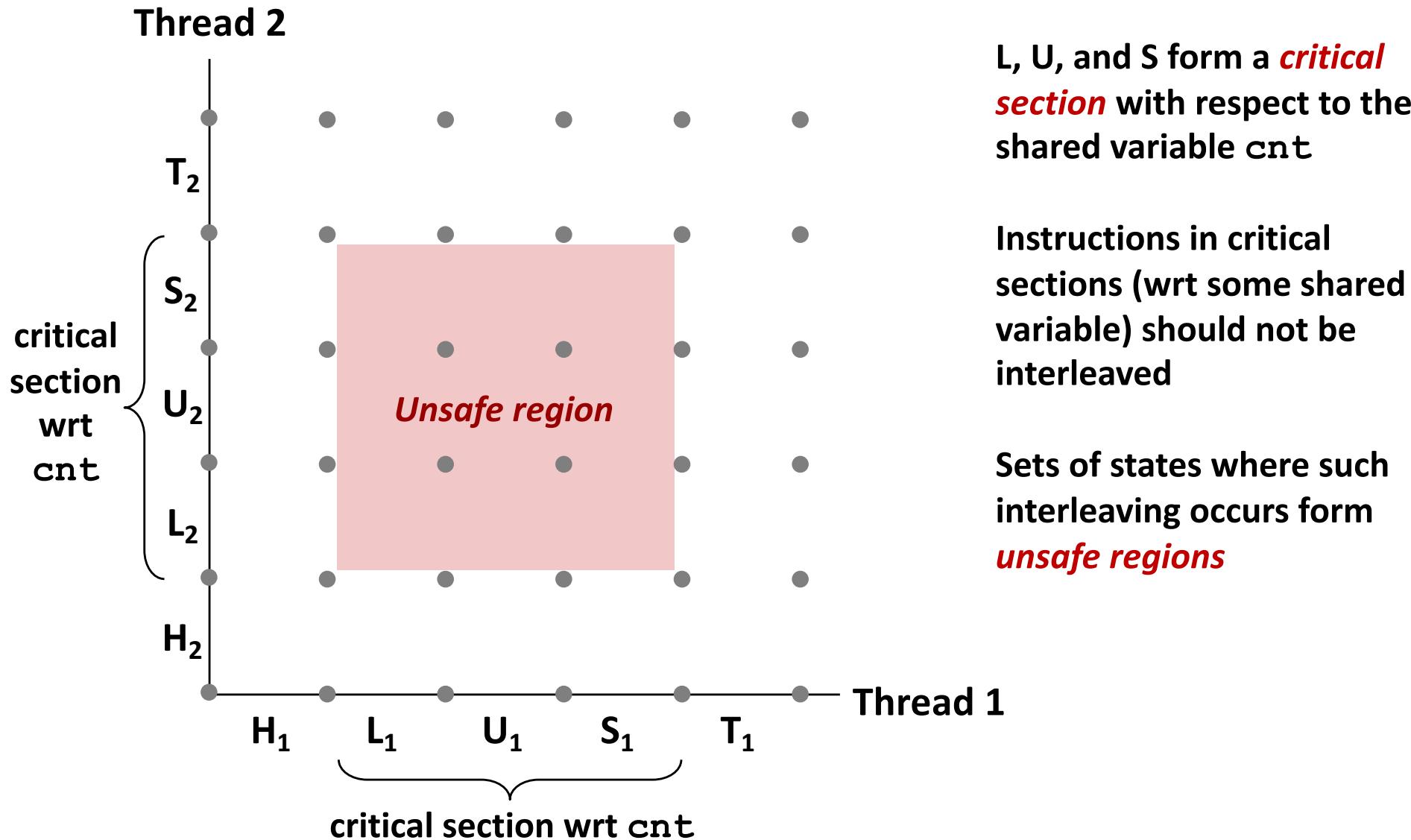


A **trajectory** is a sequence of legal state transitions that describes one possible concurrent execution of the threads.

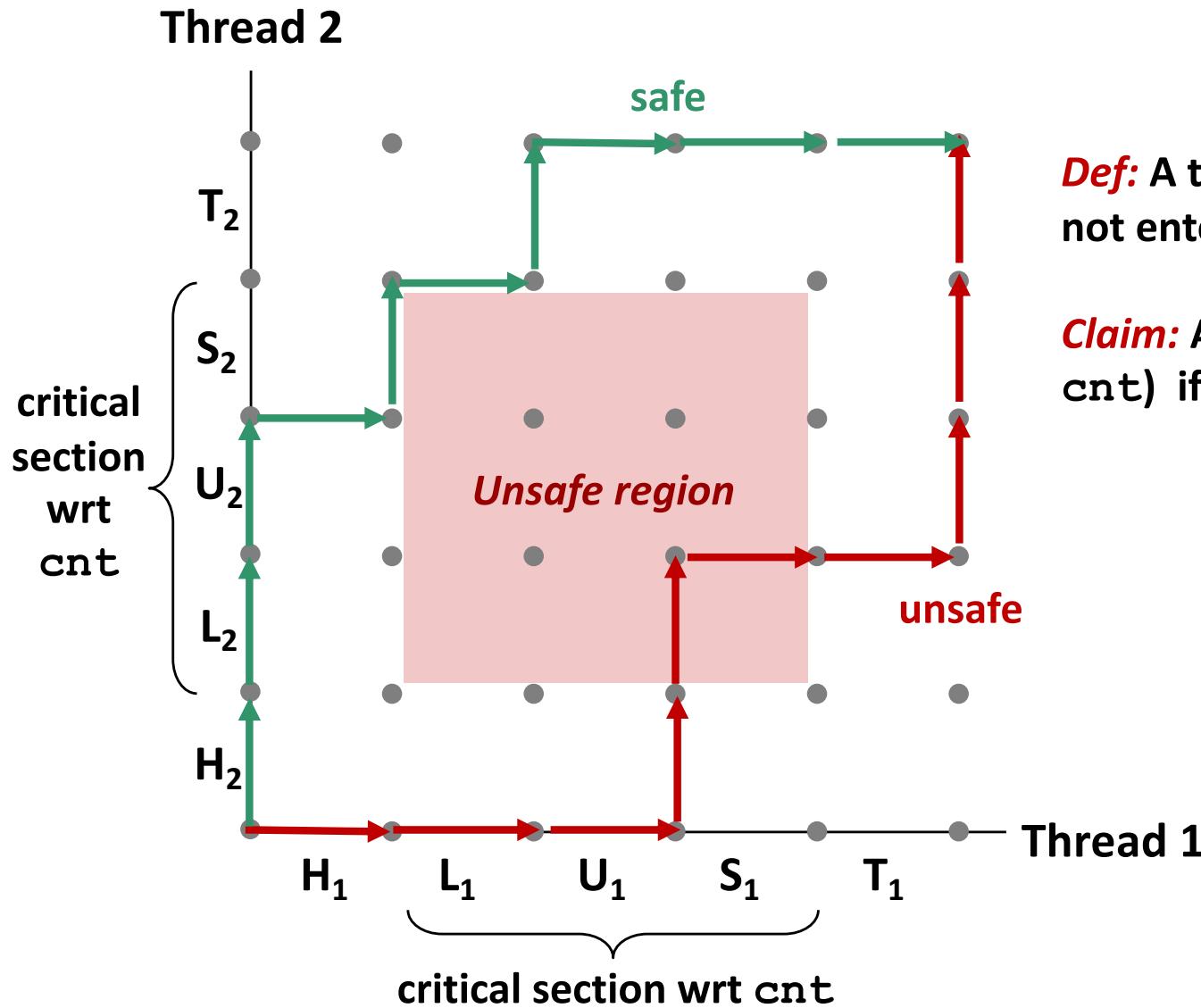
Example:

$H_1, L_1, U_1, H_2, L_2, S_1, T_1, U_2, S_2, T_2$

Critical Sections and Unsafe Regions



Critical Sections and Unsafe Regions



Def: A trajectory is **safe** iff it does not enter any unsafe region

Claim: A trajectory is **correct (wrt cnt)** iff it is safe

Enforcing Mutual Exclusion

- **Question:** How can we guarantee a safe trajectory?
- **Answer:** We must *synchronize* the execution of the threads so that they can never have an unsafe trajectory.
 - i.e., need to guarantee *mutually exclusive access* for each critical section.
- **Classic solution:**
 - Semaphores (Edsger Dijkstra)
- **Other approaches (out of our scope)**
 - Mutex and condition variables (Pthreads)
 - Monitors (Java)

Semaphores

- **Semaphore:** non-negative global integer synchronization variable. Manipulated by P and V operations.
- $P(s)$
 - If s is nonzero, then decrement s by 1 and return immediately.
 - Test and decrement operations occur atomically (indivisibly)
 - If s is zero, then suspend thread until s becomes nonzero and the thread is restarted by a V operation.
 - After restarting, the P operation decrements s and returns control to the caller.
- $V(s)$:
 - Increment s by 1.
 - Increment operation occurs atomically
 - If there are any threads blocked in a P operation waiting for s to become nonzero, then restart exactly one of those threads, which then completes its P operation by decrementing s .
- **Semaphore invariant: $(s \geq 0)$**

C Semaphore Operations

Pthreads functions:

```
#include <semaphore.h>

int sem_init(sem_t *s, 0, unsigned int val); /* s = val */
int sem_wait(sem_t *s); /* P(s) */
int sem_post(sem_t *s); /* V(s) */
```

CS:APP wrapper functions:

```
#include "csapp.h"

void P(sem_t *s); /* Wrapper function for sem_wait */
void V(sem_t *s); /* Wrapper function for sem_post */
```

badcnt.c: Improper Synchronization

```
/* Global shared variable */
volatile long cnt = 0; /* Counter */

int main(int argc, char **argv)
{
    long niters;
    pthread_t tid1, tid2;

    niters = atoi(argv[1]);
    Pthread_create(&tid1, NULL,
                   thread, &niters);
    Pthread_create(&tid2, NULL,
                   thread, &niters);
    Pthread_join(tid1, NULL);
    Pthread_join(tid2, NULL);

    /* Check result */
    if (cnt != (2 * niters))
        printf("BOOM! cnt=%ld\n", cnt);
    else
        printf("OK cnt=%ld\n", cnt);
    exit(0);
}
```

badcnt.c

```
/* Thread routine */
void *thread(void *vargp)
{
    long i, niters =
        *((long *)vargp);

    for (i = 0; i < niters; i++)
        cnt++;

    return NULL;
}
```

How can we fix this using semaphores?

Using Semaphores for Mutual Exclusion

■ Basic idea:

- Associate a unique semaphore *mutex*, initially 1, with each shared variable (or related set of shared variables).
- Surround corresponding critical sections with $P(\text{mutex})$ and $V(\text{mutex})$ operations.

■ Terminology:

- *Binary semaphore*: semaphore whose value is always 0 or 1
- *Mutex*: binary semaphore used for mutual exclusion
 - P operation: “*locking*” the mutex
 - V operation: “*unlocking*” or “*releasing*” the mutex
 - “*Holding*” a mutex: locked and not yet unlocked.
- *Counting semaphore*: used as a counter for set of available resources.

goodcnt.c: Proper Synchronization

- Define and initialize a mutex for the shared variable cnt:

```
volatile long cnt = 0; /* Counter */  
sem_t mutex; /* Semaphore that protects cnt */  
  
Sem_init(&mutex, 0, 1); /* mutex = 1 */
```

- Surround critical section with *P* and *V*:

```
for (i = 0; i < niters; i++) {  
    P(&mutex);  
    cnt++;  
    V(&mutex);  
}
```

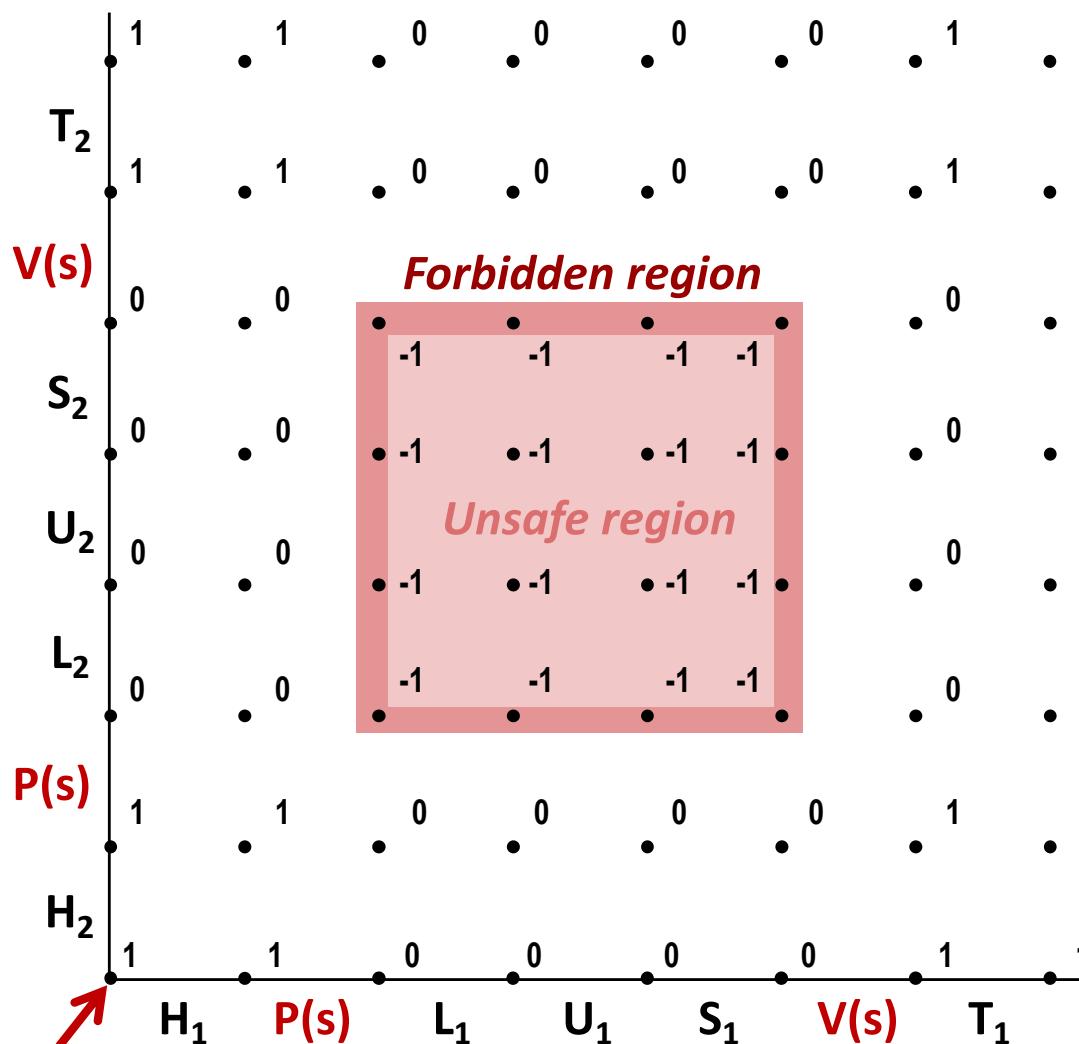
goodcnt.c

```
linux> ./goodcnt 10000  
OK cnt=20000  
linux> ./goodcnt 10000  
OK cnt=20000  
linux>
```

Warning: It's orders of magnitude slower
than badcnt.c.

Why Mutexes Work

Thread 2



Provide mutually exclusive access to shared variable by surrounding critical section with P and V operations on semaphore s (initially set to 1)

Semaphore invariant creates a **forbidden region** that encloses unsafe region and that cannot be entered by any trajectory.

Initially

$$s = 1$$

Summary

- Programmers need a clear model of how variables are shared by threads.
- Variables shared by multiple threads must be protected to ensure mutually exclusive access.
- Semaphores are a fundamental mechanism for enforcing mutual exclusion.