# COMP3630/6360: Theory of Computation 

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The Australian National University

Turing Machines

## This lecture covers Chapter 8 of HMU: Turing Machines

> Turing Machine
> Extensions of Turing Machines
> Restrictions of Turing Machines

Additional Reading: Chapter 8 of HMU.

## Turing Machine: Informal Definition


> An tape extending infinitely in both sides
>A reading head that can edit tape, move right or left.
>A finite control.
>A string is accepted if finite control reaches a final/accepting state

## Turing Machine: Formal Definition

A Turing machine $M=\left(Q, \Sigma, \Gamma, \delta, q_{0}, B, F\right)$ comprises of:
$>Q$ : finite set of states
> $\Sigma$ : finite set of input symbols
$>\Gamma$ : finite set of tape symbols such that $\Sigma \subseteq \Gamma$
$>\delta$ : transition function. $\delta$ is a partial function over $Q \times \Gamma$, where the first component is viewed as the present state, and the second is viewed as the tape symbol read. If $\delta(\boldsymbol{q}, \boldsymbol{X})$ is defined, then

$>B \in \Gamma \backslash \Sigma$ is the blank symbol. All but a finite number of tape symbols are $B$ s.
$>q_{0}$ : the initial state of the TM.
> $F$ : the set of final/accepting states fo the TM.
>Head always moves to the left or right. Being stationary is not an option.
> The Turing Machine is deterministic.

## Describing TMs

> Turing machines can be defined by describing $\delta$ using a transition table.
> They can also be defined using transition diagrams (with labels appropriately altered)

$$
X / Y D
$$

$$
\text { If } \delta(q, X)=\left(q^{\prime}, Y, D\right)
$$



## A TM that accepts any binary string that does not contain 111



## Instantaneous Descriptions of TMs

>An instantaneous description (or configuration) of a TM is a complete description of the system that enables one to determine the trajectory of the TM as it operates.
> The instantaneous description or configuration or ID of a TM contains 3 parts: (a) The (finite, non-trivial) portion of tape to the left of the reading head; (b) the state that the TM is presently in; and (c) the (finite, non-trivial) portion of the tape to the right of the reading head.


## ‘Moves’ of a TM

> Just as in the case of a PDA, we use $\vdash_{M}$ to indicate a single move of a TM $M$, and $\stackrel{*}{\stackrel{H}{M}^{*}}$ to indicate zero or a finite number of moves of a TM.

Present ID

$$
\begin{gathered}
X_{1} \cdots X_{i-1} q X_{i} \cdots X_{\ell} \\
(1<i<\ell)
\end{gathered}
$$

$$
X_{1} \cdots X_{\ell} B^{i-1} q
$$

$$
q B^{i} X_{1} \ldots X_{\ell}
$$

$$
\begin{aligned}
& \delta\left(q, X_{i}\right)=\left(q^{\prime}, Y, R\right) \quad X_{1} \cdots X_{i-1} Y q^{\prime} X_{i+1} \cdots X_{\ell} \\
& \delta\left(q, X_{i}\right)=\left(q^{\prime}, Y, L\right) \quad X_{1} \cdots X_{i-2} q^{\prime} X_{i-1} Y X_{i+1} \cdots X_{\ell} \\
& \delta(q, B)=\left(q^{\prime}, Y, R\right) \quad X_{1} \cdots X_{\ell} B^{i-1} Y q^{\prime} \\
& \delta(q, B)=\left(q^{\prime}, Y, L\right) \quad \begin{cases}X_{1} \cdots X_{\ell-1} q^{\prime} X_{\ell} Y & i=1 \\
X_{1} \cdots X_{\ell} B^{i-2} q^{\prime} B Y & i>1\end{cases} \\
& \delta(q, B)=\left(q^{\prime}, Y, R\right) \quad\left\{\begin{array}{l}
Y q^{\prime} X_{2} \cdots X_{\ell} \quad i=0 \\
Y q^{\prime} B^{i-1} X_{1} \cdots X_{\ell} \quad i>0
\end{array}\right. \\
& \delta(q, B)=\left(q^{\prime}, Y, L\right) \quad\left\{\begin{array}{l}
q^{\prime} B Y X_{2} \cdots X_{\ell} \quad i=0 \\
q^{\prime} B Y B^{i-1} X_{1} \cdots X_{\ell} \quad i>0
\end{array}\right.
\end{aligned}
$$

## Next ID

Language accepted by a TM
>A string $w$ is in the language accepted by a TM $M$ iff $q_{0} w \stackrel{*}{\vdash_{M}} \alpha p \beta$ for some $p \in F$.
>Another notion of acceptance that is common is to require a TM to halt (i.e., no further transitions are possible).
> It is always possible to design a TM such that the TM halts when it reaches a final state without changing the language the TM accepts.
> However, we cannot require (all) TMs to halt for all inputs.
> A language $L$ is recursively enumerable if it is accepted by some TM.
>A language $L$ is recursive if it is accepted by a TM that always halts on its input.


## Extensions of TMs

## Multiple-Track TMs

## Multiple-track TM

> There are $k$ tracks, each having symbols written on them.
> The machine can only read symbols from each tape corresponding to one location, i.e., all symbols in a column at any one time.
> A k-track TM with tape alphabet $\Gamma$ has the same langauge-acceptance power as a TM with tape alphabet $\Gamma^{k}$.

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## Multi-tape TMs

## Multiple-tape TM

> There are $k$ tapes, each having symbols written on them.
> The machine can each tape independently, i.e., the symbols read from each tape need not correspond to the same location
> After a read of each tapes, each reading head can move independently to the right, left, or stay stationary.


## Multi-tape TMs

## Theorem 7.1.1

Every language that is accepted by a multi-tape TM is also recursively enumerable (i.e., accepted by some 'standard' TM).

## Proof of Theorem 7.1.1

> Let $L$ be accepted by a $k$-tape TM $M$. We'll devise a $2 k$-track TM $M^{\prime}$ that accepts $L$.
> Every even tape of $M^{\prime}$ has the same alphabet as that of the $k$-tape TM. The $2 i^{\text {th }}$ track of $M^{\prime}$ contains exactly the same contents as the $i^{\text {th }}$ tape of $M$.
> Every odd track has an alphabet $\{B, \dagger$,$\} , and contains a single \dagger$. The $2 i-1^{\text {th }}$ track of $M^{\prime}$ contains $\dagger$ at the location where the $i^{\text {th }}$ reading head of $M$ is located.



## Multi-tape TMs

## Proof of Theorem 7.1.1

> The state of $M^{\prime}$ has 3 components: (a) the state of $M$; (b) the number of $\dagger s$ to its strict left; and (c) a vector of length $k$ with each component taking value in $\Gamma \cup\{?\}$.
> Each move of $M$ takes multiple moves of $M^{\prime}$, and is a sweep of the tape from the location of the leftmost $\dagger$ to that of the rightmost $\dagger$ and back performing the changes to tracks that $M$ would do to its corresponding tapes.
>At the beginning of the sweep, the head of $M^{\prime}$ is at a location where the leftmost $\dagger$ is and the state of $M^{\prime}$ is $(q, 0,[?, \cdots, ?])$. The head moves to the right uncovering $\dagger$ s and the corresponding track symbols (are stored in the third component of the state).
> The right sweep ends when the second component is $k$.


State: $\left(q_{0}, 0,[0,1,1]\right)$


State: $q_{0}$

## Multi-tape TMs

## Proof of Theorem 7.1.1

> At this stage, $M^{\prime}$ knows the input symbols $M$ will have read, and knows what actions to take.
> It then sweeps left making appropriate changes to the tracks (just like $M$ does to its tape) each time a $\dagger$ is encountered. $M^{\prime}$ also moves the $\dagger$ s accordingly.
> The left sweep ends when the second component is zero. At this time, $M^{\prime}$ would have completed moving the $\dagger \mathrm{s}$ and the track contents; they'll now match those of $M$.
> $M^{\prime}$ then moves the state to $\left(q^{\prime}, 0,[?, \cdots, ?]\right)$ and start the next sweep if $q^{\prime}$ is not a final state.
> Note that $M^{\prime}$ mimics $M$ and hence the languages accepted are identical.

## Multi-tape TMs

> The running time of a TM $M$ with input $w$ is the number of moves $M$ makes before it halts. (If it does not, the running time is $\infty$ ).
> The time complexity $T_{M}:\{0,1, \ldots\} \rightarrow\{0,1, \ldots\}$ of a TM $M$ is defined as follows:
$>T_{M}(n):=$ maximum running time of $M$ for an input $w$ of length $n$ symbols.

## Theorem 7.1.2

The time taken for $M^{\prime}$ in Theorem 7.1.2 to process $n$ moves of $M$ is $O\left(n^{2}\right)$.

## Outline of Proof of Theorem 7.1.2

> After $n$ moves of $M$, any two heads of $M$ can be at most $2 n$ locations apart.
> Each sweep then requires $4 n$ moves of $M^{\prime}$.
> Each track update requires a finite number of moves. Totally, to update the tracks, $\Theta(k)$ time steps are needed.


## Non-deterministic TMs

Non-deterministic TM: $\delta(q, X)$ is a set of triples representing possible moves.

## Theorem 7.1.3

For every non-deterministic TM $M$, there is a TM $N$ such that $L(M)=L(N)$.

## Outline of Proof of Theorem 7.1.3



Tape 1


## Outline of Proof of Theorem 7.1.3

> We can devise a 2-tape TM $M$ that simulates $N$.
>M first replaces the content of the first tape by $\ddagger$ followed by the ID that $N$ is initially in, which is then followed by a special symbol $\dagger$, which serves as ID separator. ( $M$ uses the second tape as scratch tape to enable this operation).
> If the ID corresponds to a final state, $N$ halts (as would $M$ ).
> If not, $M$ then identifies all possible choices for the next IDs for $N$ and enters each one of them followed by $\dagger$ at the right end of it's first tape. (Again, $M$ uses the second tape as scratch tape to enable this operation)
> $M$ then searches for $\dagger$ to the right of $\ddagger$, changes the $\dagger$ to a $\ddagger$ (to signify that it is processing the succeeding ID), and processes that ID in the similar way.
> $M$ halts at an ID iff $M$ would at that ID.

## Restrictions of TMs

## Theorem 7.2.1

Every recursively enumerable language is also accepted by a TM with semi-infinite tape.

## Outline of Proof of Theorem 7.2.1

> Given a TM $M$ that accepts a language $L$, construct a two-track TM $M^{\prime}$ as follows.
> The first and second tracks of $M^{\prime}$ are the R and L semi-infinite parts of the tape of $M$.
> First, write a special symbol, say $\dagger$ at the leftmost part of the second track; this indicates to $M^{\prime}$ that a left move is not to be attempted at this location.
>At any time, $M^{\prime}$ keeps track of whether $M$ is to the right or left of its start location.
> If $M$ is to the strict right of its start location, $M^{\prime}$ mimics $M$ on the first track. If $M$ is to the strict left of its start location, $M^{\prime}$ mimics $M$ on second track, but with the head directions reversed. $M^{\prime}$ detects the start by the $\dagger$ symbol.
> It can be formally shown that $M^{\prime}$ accepts a string iff $M$ accepts it.


## Multi-stack Machines

A multistack machne is a PDA with several independent stacks (i.e., one can be popping a symbol, while the other is writing a symbol).

## Theorem 7.2.2

Every recursively enumerable language is accepted by a two-stack PDA
Outline of Proof of Theorem 7.2.2

$>\dagger$ indicates the end of the stack content (to prevent PDA from halting)
> If TM moves right changing tape symbol $X$ to $Y$ and state from $q$ to $q^{\prime}$, PDA moves from state $q$ to $q^{\prime}$ popping $X$ from left stack and pushing $Y$ to the right stack.

## Counter Machines

>A counter machine is a multi-stack machine whose stack alphabet contains two symbols: $Z_{0}$ (stack end marker) and $X$
$>Z_{0}$ is initially in the stack.
$>Z_{0}$ may be replaced by $X^{i} Z_{0}$ for some $i \geq 0$
$>X$ may be replaced by $X^{i}$ for some $i \geq 0$.
>A counter machine effectively stores a non-negative number.


## Counter Machines

## Theorem 7.2.3

Every recursively enumerable language is accepted by a three-counter machine

## Outline of Proof of Theorem 7.2.3

> We know a two-stack PDA can simulate any TM.
> We'll show that a 3-counter machine can simulate any (two stack) PDA.
$>$ WLOG, let the stack alphabet of $\Gamma=\{0,1, \ldots, r-1\}$.
>Suppose the first stack contains $Y_{1}$ (top) $, \ldots, Y_{k}$. Then the first counter stores $Y_{1}+r Y_{2}+\cdots+r^{k-1} Y_{k}$. Similarly for the second stack.
> The third counter is used to change the two stack contents.
> Popping the top symbol a stack (say A) = finding quotient when $Y_{1}+r Y_{2}+\cdots+r^{k-1} Y_{k}$ is divided by $r$.
> pop $r$ X's from stack $A$, and push a single $X$ on the third stack. Repeat until all $X \mathrm{~s}$ are exhausted on the stack where popping is performed.
> Now empty stack A and copy the third stack contents onto stack A.
> Change $Y_{1}$ to some $Y_{1}^{\prime}$ requires adding or subtracting, which is done by popping or pushing the corresponding number of $X \mathrm{~s}$.

## Counter Machines

## Outline of Proof of Theorem 7.2.3

> pushing a symbol $Z$ onto a stack (say $A$ ) $=$ compute $r C+Z$ where $C$ is the number presently stored in the stack $A$.
$>$ pop one $X$ from stack $A$, and push $r X$ s on the third stack.
> Finally push Z Xs onto the third stack. Now empty stack A and copy the third stack contents onto stack A.
> Since the above three are the only operations needed to simulate a TM on a two-stack PDA, we can stimulate a 2-stack PDA and hence a TM using a 3-counter machine.

## Theorem 7.2.4

Every recursively enumerable language is accepted by a two-counter machine

## Outline of Proof of Theorem 7.2.4

> The key idea: simulate three counters using one, and use the other for manipulations.
> The first counter stores $2^{i} 3^{j} 5^{k}$ where $i, j, k$ are the contents of the 3 -counter machine.
> Updates to the stack involve: (a) divide by 2,3 , or 5 ; (b) multiply by 2,3 , or 5 ; or (c) identify if $i$ or $j$ or $k$ is zero (check divisibility).
> Each operation can be easily seen to be done with a spare counter.

