SHARED MEMORY PARALLEL COMPUTING

COMP4300/8300 PARALLEL SYSTEMS

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Simultaneous Multi-Threading (SMT or Hyperthreading) and Single-Instruction Multiple Data (SIMD)

Logistics

Attendance to the Lab sessions is highly encouraged. Most of the practical aspects of the programming models are covered in the Labs.



Reference Material

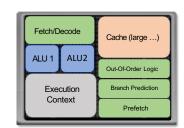
- > Introduction to High Performance Computing for Scientists and Engineers, Hager and Wellein
- ➤ Using OpenMP The Next Step, R. van der Pas, E. Stotzer, and C. Terboven, Chapter 4
- Intel Intrinsics Guide, https://www.intel.com/content/www/us/en/docs/intrinsicsguide/index.html
- Chapter 4 from Computer Systems A Programmer's Perspective, Third Edition, Randal E. Bryant and David R. O'Hallaron, Pearson Education Heg USA, ISBN 9781292101767.





Simple Single Core Superscalar CPU Architecture

- > Multiple fetch/decode units
- ➤ Multiple ALUs, in general multiple Functional Units (FUs)
- ➤ One Execution Context (EC)
- > Exploits Instruction Level Parallelism (ILP) through superscalarity and pipelining
- > ILP requires sophisticated, additional logic to yield good performance
 - > Out-of-Order (OoO) execution
 - ➤ Pre-fetching
 - > Branch prediction
 - ➢ Big caches
- > This extra logic is tightly coupled to the FUs and to the EC
- > Thus, this view of the CPU architecture is too simplistic





A real single core architecture

The front end retrieves the instructions from memory and translates instructions into a format that can be understood by other components of the CPU.

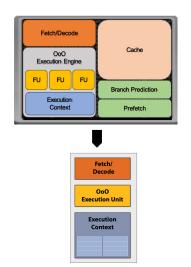
Intel Skylake

The execution unit is the part of the CPU that actually carries out the execution that can be understood to the components of the CPU.

L2 Cache

More schematic single core architecture

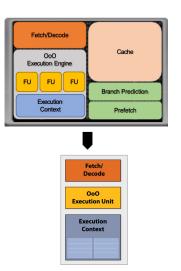
- In the real core architecture Functional Units, Out-of-Order Execution Logic, Execution Context are tightly coupled at the hardware level
- ➤ Map Front End to Fetch/Decode
- Map Execution Engine to Functional Units plus Out-of-Order Execution Logic plus Execution Context
- Leave the rest of the logic, Branch Predictor, Caches, Prefetching out of our representation



Under utilisation of ILP

instructions

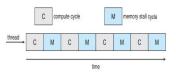
What are the main causes of under utilisation of ILP on this single-core architecture?

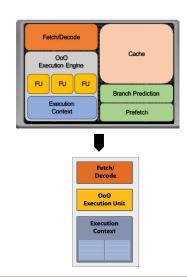




Under utilisation of ILP

- ➤ The main causes of under utilisation of ILP on this single-core architecture: -
 - > Branch misprediction
 - ➤ Bad instruction mix → cannot feed all replicates of the functional units
 - ➤ Thread stalls due to dependencies → thread cannot execute as it is waiting for operands to be fetched or dependencies to be resolved

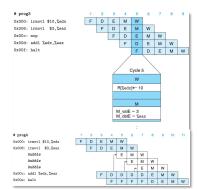






Under utilisation of ILP

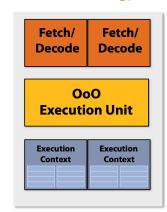
- Pipeline Hazards: The next stage in the pipeline cannot execute in the following clock cycle
- > Typically caused by dependencies between successive instructions
- Data dependencies: the results computed by one instruction are used as the input data for a following instruction
- Control dependencies: one instruction determines the location of the following instruction (e.q, jump, return)
- This can require the hardware to insert no-ops called bubbles in the pipeline, causing it to stall while the dependencies are resolved



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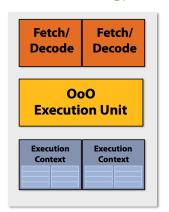
Hyperthreading (Simultaneous Multi-Threading)

- ➤ Idea: Interleave processing of multiple threads on the same core to hide stalls
- ➤ This can hide the latency of one thread's stalls with another thread's execution
- ➤ What is a potential problem with this strategy?



Hyperthreading (Simultaneous Multi-Threading)

- ➤ Idea: Interleave processing of multiple threads on the same core to hide stalls
- ➤ This can hide the latency of one thread's stalls with another thread's execution
- ➤ What is a potential problem with this strategy? ... *Context switch*

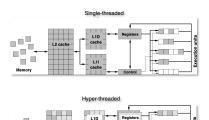






Hyperthreading: A More Detailed View

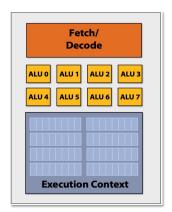
- > What is a potential problem with this strategy? Context switch -->
- > Add dedicated separated execution contexts for these threads
- > Since the contexts of these threads are in dedicated register space, context switch is either lightweight or for free
- → simultaneous multi-threading





Single Instruction Multiple Data (SIMD)

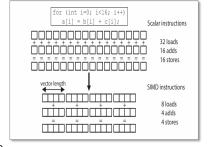
- ➤ Idea "2": Amortize cost/complexity of managing an instruction stream across many ALUs
- Single Instruction Multiple Data (SIMD) processing
- > Fetch and decode one instruction
- > Same instruction broadcast and executed in parallel on ALUs operating on different data elements
- > Execution context must be larger, for example make registers larger (in bits)
- > This requires different instructions



Introduction to SIMD

SIMD provides data-parallelism at the instruction level

- > A single instruction operates on multiple data elements in parallel SIMD instructions use special registers a larger width (vector length)
- > SIMD instructions are as fast as their scalar counterpart, leading to potential speedup of up to the vector length
- > In practice, the speedup achieved may depend heavily on memory operations needed to move the data



Using SIMD Capabilities

Vector Extensions or Intrinsics

- Vendor provided code extensions close to assembly level
- > Advantages: Provide performance and control
- > Disadvantages: Extremely verbose, generally not portable

Compiler Flags

- > Advantages: No additional coding effort
- > Disadvantages: Vendor specific, performance and success compiler-dependent, problematic for complex code, almost no control on implementation

OpenMP SIMD

- > Pragmas in OpenMP for implementing SIMD parallelism
- Advantages: Portable, concise and easy to use
- > Disadvantages: Performance compiler-dependent, correctness left to programmer, no low-level control on implementation





Vector Extensions (Intrinsics)

SSE instructions: 128-bit operations: 4x32 bits or 2x64 bits (4-wide float vectors)

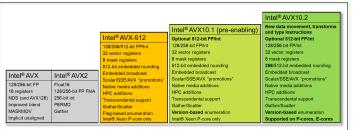
AVX instructions: 256-bit operations: 8x32 bits or 4x64 bits (8-wide float vectors)

AVX512: 512-bit operations: 16x32 bits or 8x64 bits (16-wide float vectors)



Vector Extensions (Intrinsics)

SSE instructions: 128-bit operations: 4x32 bits or 2x64 bits (4-wide float vectors) AVX instructions: 256-bit operations: 8x32 bits or 4x64 bits (8-wide float vectors) AVX512: 512-bit operations: 16x32 bits or 8x64 bits (16-wide float vectors)



The Converged Vector ISA: Intel® Advanced Vector Extensions 10

Figure 1-2. Intel® ISA Families and Features

Scalar program

```
void sinx (int N, int terms, float * x, float * result)
 for (int i = 0; i < N; i ++)</pre>
   float value = x[i];
  float numer = x[i] * x[i] * x[i];
int denom = 6; // 3!
   int sign = -1;
   for (int j=1; j <= terms; j++)
     value += sign * numer / denom;
     numer *= x[i] * x[i];
denom *= (2*j+2) * (2*j+3);
     sign *= -1;
   result [i] = value;
```

Vector Program Using AVX2 Intrinsics

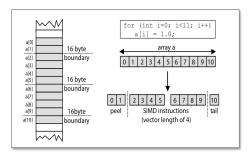
```
#include <immintrin.h>
void sinx (int N, int terms, float * x, float * result)
  float three_fact = 6; // 3!
  for (int i=0; i<N; i+=8)
    _m 256 origx = _mm 256 _load_ps (&x[i]);
    m256 value = origx;
    __m256 numer = mm256_mul_ps(origx, mm256_mul_ps(origx, origx));
_m256 denom = _mm256_set1ps(three_fact); float sign = -1;
for (int ]=1; j<=erms; j++)
       // value += sign * numer / denom
       _m 256 tmp = _mm 256_div_ps(_mm 256_mul_ps(_mm 256_set1ps(sign), numer), denom);
value = _mm 256_add_ps(value, tmp);
       numer = _mm 256 mul ps (numer, _mm 256 mul ps (origx, origx));
denom = _mm 256 mul ps (denom, _mm 256 _set1ps ((2*j+2) * (2*j+3)));
      mm 256 store ps (& result [i], value);
```



Alignment

To get full benefit from SIMD the starting address of the vectors (arrays) needs to be aligned on a correct memory address boundary

- > Starting array address in memory must be a multiple of the SIMD length
- No optimal alignment → compiler has to use loop peeling
- Loop peeling generates a loop peel and (usually) a loop tail that is treated separately
- The peel and tail section are typically not executed using SIMD instructions



Demo

Vector Program Using AVX2 Intrinsics

Challenges for compiler vectorization

The compiler can identify operations suitable for vectorization (or you can give it a hint using OpenMP directives), but it must prove that it is a legal operation.

The following issues tend to prevent the compiler from vectorizing your code:

- Imprecise dependence information (potential pointer aliasing)
- > Bad data layout and alignment
- Branching
- > Calls to functions
- > Loop bounds that are not multiples of the SIMD length

The simd construct

- > The OMP compiler may transform a loop marked with the simd construct into a SIMD loop.
- A SIMD chunk of iterations (equal to the SIMD length) is executed by a single thread
- Within a chunk each iteration is executed by a SIMD lane
- The following clauses are supported on the simd construct

```
private (list)
lastprivate (list)
reduction (reduction-identifier : list)
collapse (n)
simdlen (length)
safelen (length)
linear (list/:linear-step/)
aligned (list/:alignment/)
```



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- > The following clauses are supported on the simd construct

```
private (list)
lastprivate (list)
reduction (reduction-identifier: list)
collapse (n)
simdlen (length)
safelen (length)
linear (list[:linear-step])
aligned (list[:alignment])
```

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The simd construct

- > The reduction and collapse clauses works for SIMD loop as well!
- ➤ For each variable in the reduction list, a private instance is used during the execution of the SIMD loop, with all private instances being combined using the reduction operator
- When using collapse use the compiler commentary to check that vectorization was able to be performed

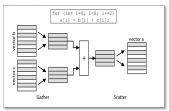
The simd construct

- If you use the simd construct, you are instructing the compiler to use SIMD instructions
- Where there is pointer aliasing your code will give incorrect results
- Where you do not provide the SIMD length through the simdlen clause, the compiler will select an appropriate vector length
- Similarly to the for construct the compiler will create a new instance of the loop variable *i* for each SIMD lane.

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Gather/scatter data in/out of vectors

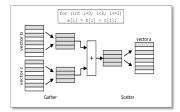
- Scalar data elements are packed into vectors, operated on collectively as a vector by SIMD instructions, and then unpacked.
- When accessing the scalar data with stride 1 (assuming optimal alignment) a single SIMD load/store instruction can be used for packing/unpacking.
- When accessing the scalar data with stride > 1, the compiler will need to write code to perform gather and scatter operations for vector packing/unpacking





Gather/scatter data in/out of vectors

- > A gather operation reads scalar data elements from memory linearly but with a stride greater than one.
- A scatter operation writes the scalar data elements in a vector back to memory linearly with a stride greater than one.
- > Some architectures support SIMD gather and scatter instruction.





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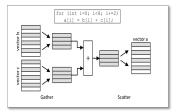
The aligned clause

#pragma omp simd aligned(list[:alignment])
for-loop

- For compiler optimizations if your arrays have been allocated at optimal alignment boundaries (e.g. aligned alloc, memalign, posix memalign)
- In C, a variable that appears in the clause must have an array or pointer type.
- In C++, a variable that appears in the clause must have array, pointer, reference to array, or reference to pointer type.

Gather/scatter data in/out of vectors

- > In general gather/scatter operations are much more expensive than single vector load/store instruction (best scenario)
- The next best scenario is when the access pattern is linear but with a stride that is greater than one and gather and scatter instructions may be used.
- The worst-case scenario is when no linear access pattern can be determined, and the scalar data elements must be individually packed into and unpacked from vectors.



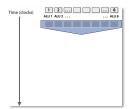
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Conditional Execution

```
<unconditional code >
float x = A[i];
if (x > 0) {
   float tmp = exp(x,5.f);
   tmp "= kMyConst1;
   x = tmp + kMyConst2;
} else {
   float tmp = kMyConst1;
   x = 2.f * tmp; }
<resume unconditional code >
   result[i] = x;
```



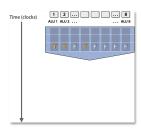
In SIMD, all processing elements execute the same instruction at the same time.





Conditional Execution

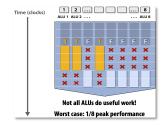
```
<unconditional code >
float x = A[i];
if (x > 0) {
   float tmp = exp(x,5.f);
   tmp *= kMyConst1;
   x = tmp + kMyConst2;
      float tmp = kMyConst1;
      x = 2.f * tmp; }
<resume unconditional code > result[i] = x;
```



When a conditional statement, e.g. an if statement, causes the control flow to diverge (i.e., some processing elements need to execute one instruction while others need to execute a different instruction), this can lead to inefficiencies

Conditional Execution





Many processing elements might have to remain idle, which can reduce the overall performance (throughput)

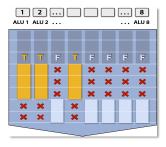
Terminology

Instruction stream coherence ("coheren"t execution)

- > Same instruction sequence applies to all elements operated upon simultaneously
- > Coherent execution is necessary for efficient use of SIMD processing resources
- > Coherent execution IS NOT necessary for efficient parallelization across cores, since each core has the capability to fetch/decode a different instruction stream

"Divergent" execution

> A lack of instruction stream coherence



SIMD Execution on CPU and GPU

Execution on CPU

- > Explicit SIMD execution: SIMD parallelization is performed at compile time. Instructions are generated by the compiler (e.g., AVX512 instructions)
 - Parallelism explicitly requested by programmer using intrinsics
 - > Parallelism conveyed using parallel language semantics (e.g., pragma omp simd)
 - > Parallelism inferred by dependency analysis of loops (hard problem, even best compilers are not great on arbitrary C/C++ code)

Execution on GPU

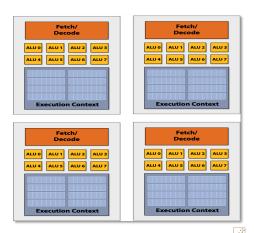
- > Implicit SIMD execution: Hardware (not compiler) is responsible for simultaneously executing the same instruction from multiple instances on different data on SIMD ALUS
- > Compiler generates a scalar binary (scalar instructions) but N instances of the program are always run together on the processor
- > SIMD width of most modern GPUs is 32
- > Divergence is a very big issue (divergent code might execute at 1/32 the peak capability of the machine!)





SIMD Multi-Core

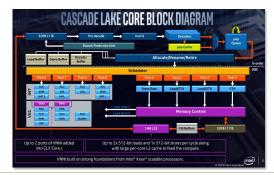
- > 4 cores
- > Each core has 8 SIMD ALUs
- > = 32 operations



SIMD Multi-Core

Cascade Lake CPUs on Gadi, Intel(R) Xeon(R) Platinum 8268 CPU @ 2.90GHz

- > 24 cores, each core 2 × AVX512 units, equivalent to 16 × 64-bit ALUs
- > Hyperthreading level 2 (enabled by default)



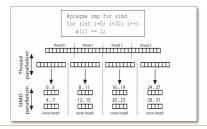


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The composite for simd construct

pragma omp for simd [clause_list]
 for - loop

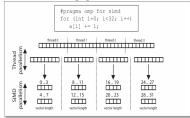
- > Chunks of loop iterations are first distributed across the threads in a team according to the clauses on the for directive (e.g. schedule)
- > Each chunk of loop iterations may be converted into SIMD loops in a way that is determined by any clauses that apply to the simd construct



The composite for simd construct

pragma omp for simd [clause_list]
 for - loop

- There may be a significantly increased memory pressure due to the fact that at runtime a new copy of each private variable will be allocated per SIMD lane.
- > Typically, the chunks performed with SIMD need to be large enough to make the loop peel/tail overhead negligible.





The composite for simd construct

```
# pragma omp for simd [ clause_list ]
    for - loop
```

- > Remember that you can use the simd schedule modifier.
- > The modifier will adjust the chunk size according to the formula ([chunk size/SIMD_length] × SIMD_width)
- > eg on AVX2 for SIMD_length = 32bits, SIMD_width = 256 bits, the chunk size will be 8
- > This ensures that the size of chunk is at least as long as the SIMD length.



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