

Optimising Virtual Machines

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Who is Loki?

- Has a Ph.D. from Sydney University
- Met Rob Pike (Inferno – Dis VM – Limbo) (see <http://vitanuova.com/> for code)
- Software Engineering / Virtual Machines
- Has written four virtual machines

Overview

- A brief definition of virtual machines
- **Stack-based vs Register-based VMs**
- An implementation of a **stack-based VM**
- An implementation of a **register-based VM**
- Performance improvement tricks
- Probably no time for JITs (but we'll see).

What are virtual machines?

- *Virtual machine vs Interpreter* – what’s the difference?
- I define an *interpreter* as “being capable of running source code, perhaps interactively”
- I define a *virtual machine* as “being capable of running code, possibly a compiled form of the code”
- An *emulator* is a virtual machine where the instruction set is based on a real CPU.

Examples of *Interpreters*

- Postscript interpreters, e.g. Ghostscript
- Lisp, Pascal interpreters
- Perl and Python languages
- DOS Batch language?
- Unix shells have a scripting language

Examples of *Virtual Machines*

- The Java VM (runs an object-oriented stack-based virtual machine language)
 - Java
 - JPython
 - Lisp
 - Prolog
- The C# VM
- Parrot is the Perl register-based VM

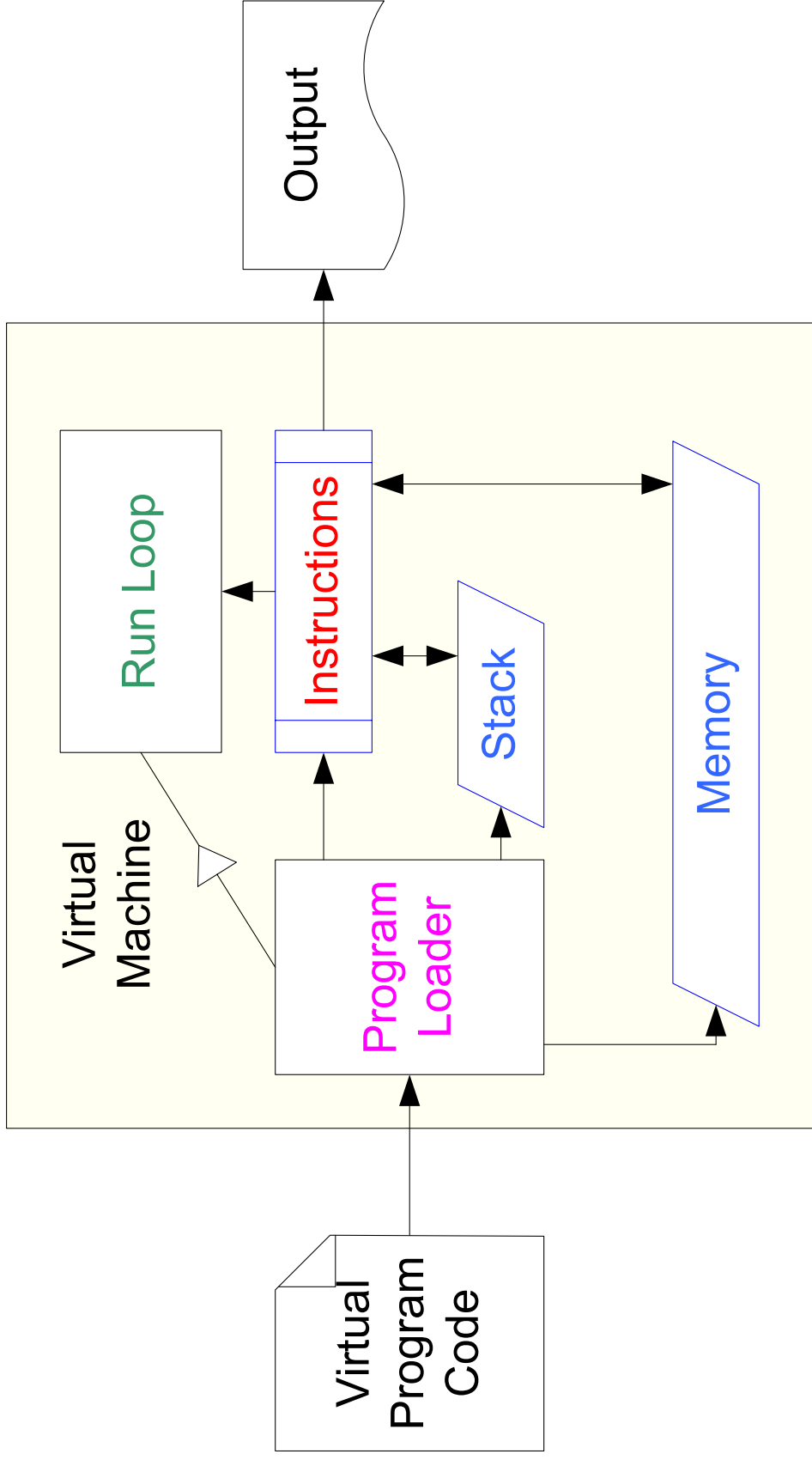
The Problem

- **Speed**
- Speed is a problem because a virtual program is:
 - *software (the program) running on*
 - *software (the VM) running on*
 - *hardware (the CPU)*
- VM performance is therefore important (but not always)

Why do people use VMs?

- Virtual machines are used for many reasons:
 - Portability (think Java and web applets)
 - Versatility (gluing disparate code together, e.g. Python, Perl, ICI)
 - String matching or regular expression parsing (e.g. Perl, ICI)
 - Emulation (I don't have the hardware, but this software VM does the same thing...)

Stack-Based VM architecture



Java VM op-code examples

- `iconst_0` push 0 (int)
- `dload_3` push local double variable 3
- `saload` push short int array elem b[a]
- `iadd` push added int (a+b)
- `lsub` push subtracted long (ab-cd)
- `frem` push remainder float (a%b)
- `ifne label` branch if int a != 0
- `ireturn` return int a from method

A simple Stack-based VM

- An instruction ‘action’ function:

```
void add_int() {  
    push(pop() + pop());  
}
```

- The execution loop:

```
void run() {  
    while (! finished) {  
        Inst *i = fetch_inst();  
        i->action();  
    }  
}
```

gcc -S output of C code on left

```
add_int:  
    call pop  
    copy r1,r3  
    call pop  
    copy r1,r4  
    add r3,r4,r2  
    call push  
    ret  
  
run:  
    jump L7test  
L7:  
    call fetch_inst  
    copy r1[12],r5  
    call r5  
L7test:  
    jeqz r9,L7
```

Tricks

- Execute as few instructions as possible within loops (include what that loop calls).
- Execute faster equivalent instructions.
- Avoid functions calls where possible.

A simpler Stack-based VM

```
void add_int() {
    *sp++ = (* (--sp) + * (--sp)); // dodgy
}

void halt() {
    exit(0);
}

void run() {
    while (true)
        (*pc++).action();
}
```

A simpler Stack-based VM

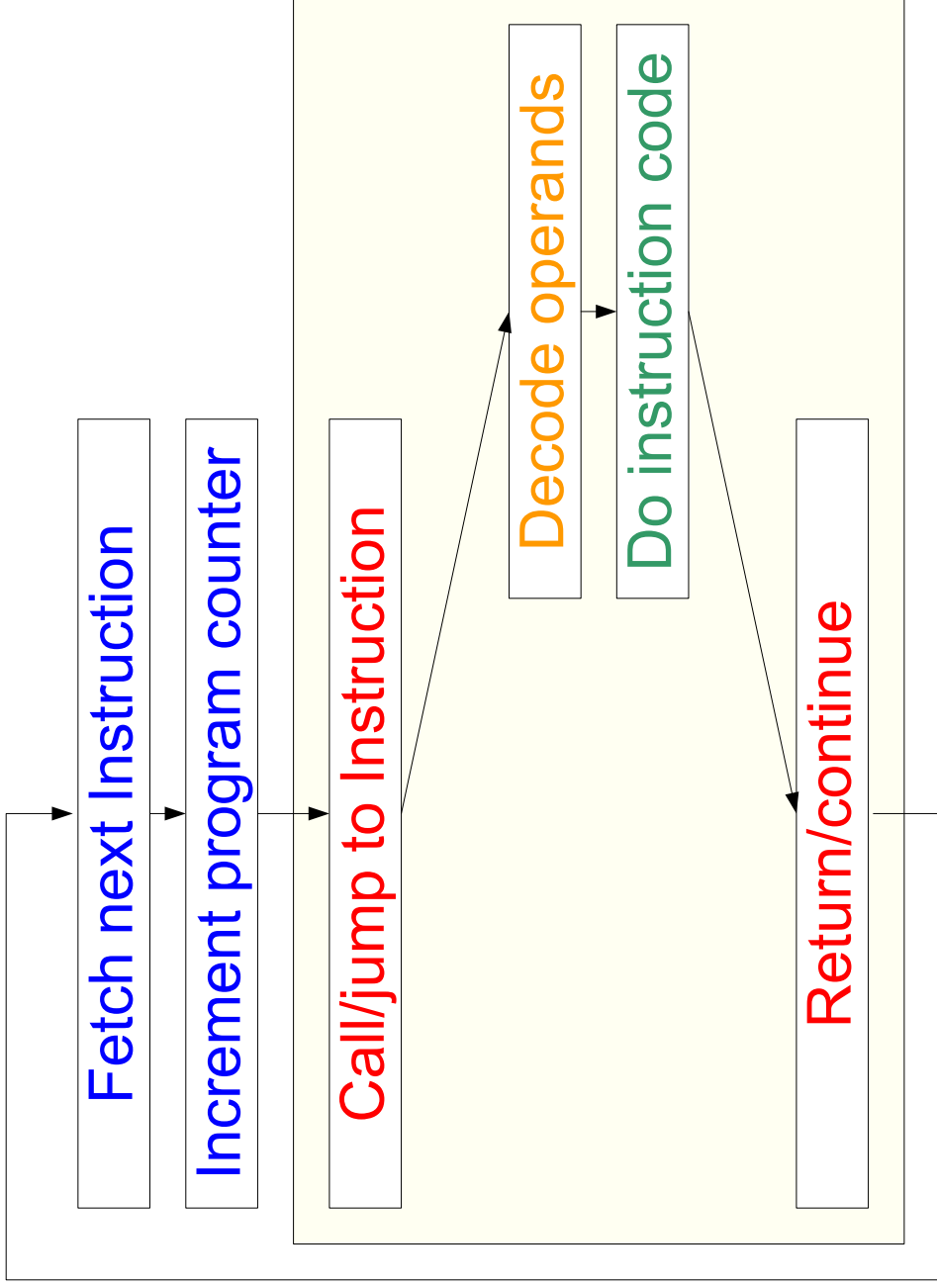
```
void add_int() {  
    int src1 = *(--sp);  
    int src2 = *(--sp);  
    *sp++ = src1 + src2;  
}
```

```
add_int:  
    dec    sp  
    copy  *sp,r3  
    dec    sp  
    copy  *sp,r4  
    add   r3,r4,*sp  
    inc   sp  
    ret
```

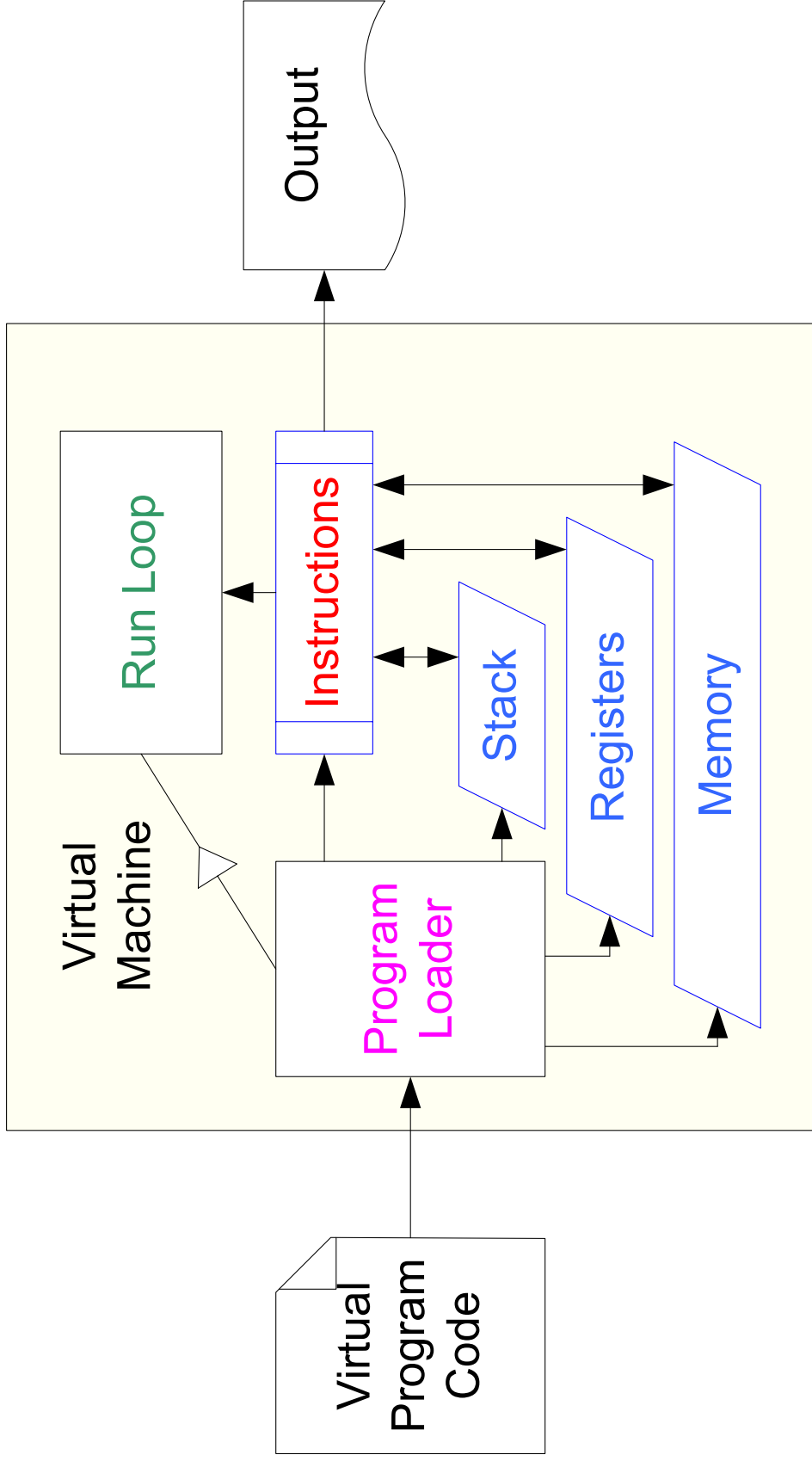
```
void run() {  
    while (true)  
        (*pc++).action();  
}
```

```
run:  
L7:    copy  pc[12],r5  
       inc   pc  
       call  r5  
       jump L7
```

VM Execution Loop



Register-Based VM architecture



A simple Register-based VM

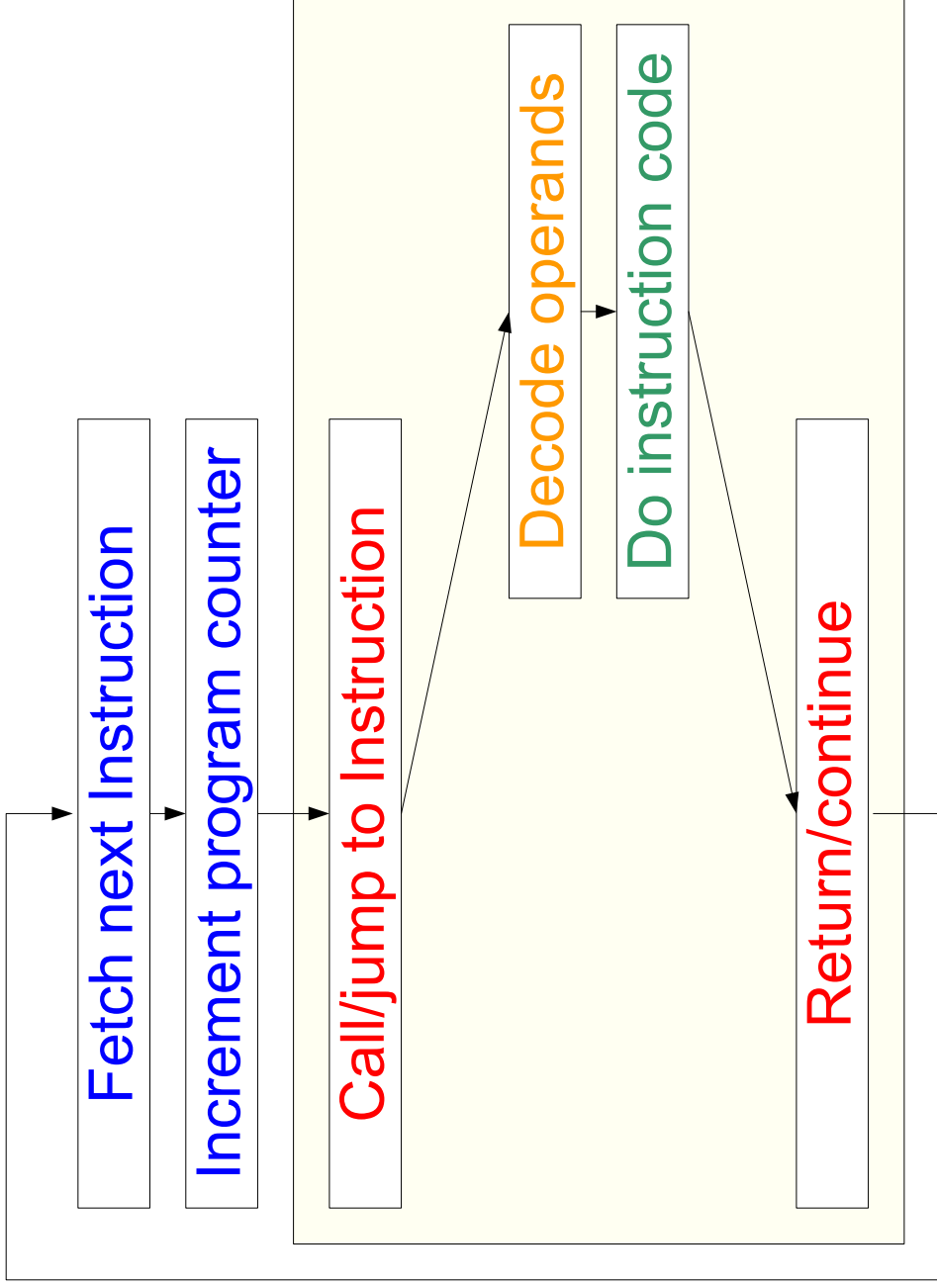
```
void add_int(int src1, int src2, int *dst) {
    *dst = src1 + src2;
}

int reg[32]; // array of registers
void run() {
    while (true) {
        Inst i = *pc++;
        i.action(reg[i.s1], reg[i.s2], &reg[i.d]);
    }
}
```

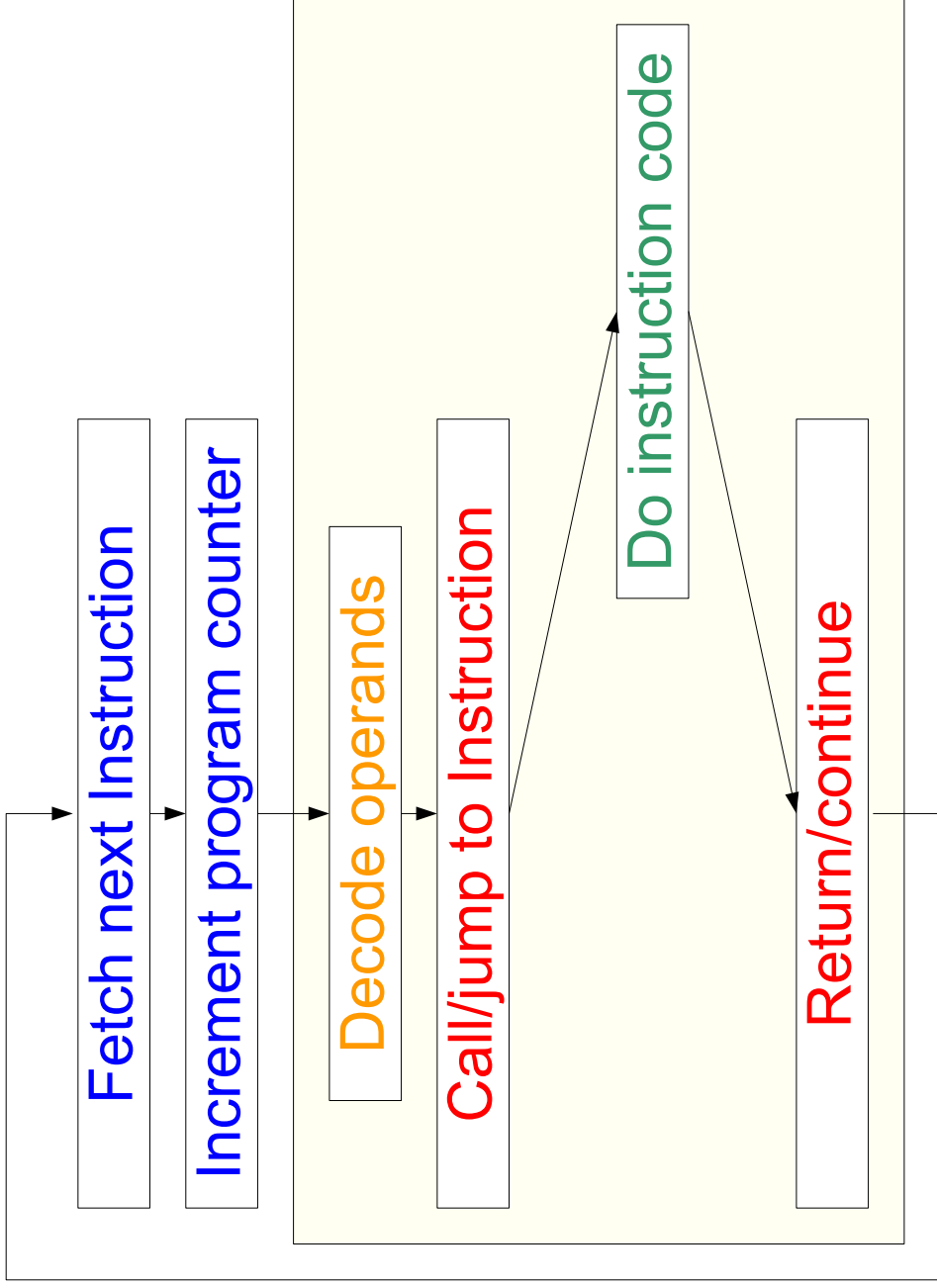
Registers vs Stacks

- Stacks:
 - Simple data model (stack = function args + locals).
 - Need extra commands to bring stack data to top.
 - JIT may be complex (real CPUs have registers).
- Registers:
 - Random access to local variables is convenient.
 - Fixed instruction function signature?
 - Real CPUs use registers. Compilers use 'em well.
 - JIT may be simpler (map VM registers onto CPU).

VM Execution Loop



VM Execution Loop 2



Decoding inside the Instruction

- **Pros:**
 - Flexibility (use only the operands you need)
 - Speed (use only the operands you need)
 - Speed (no parameters passed to the function)
- **Cons:**
 - Code size (decoding happens everywhere)
 - Complexity (decoding happens everywhere)
 - Correctness (e.g. stack overflow/underflow)

Decoding outside the Instruction

- **Pros:**
 - Security (e.g. avoid stack overflow/underflow)
 - Less code (decoding happens in one spot)
 - Correctness (decoding happens in one spot)
 - Faster to write (i.e. only the instruction)
- **Cons:**
 - Slower (introduces an if-statement into run loop?)
 - Slower (fixed number of operands to decode?)
 - Inflexibility (how many things to pop? types?)

Register-based pre-decoding VM

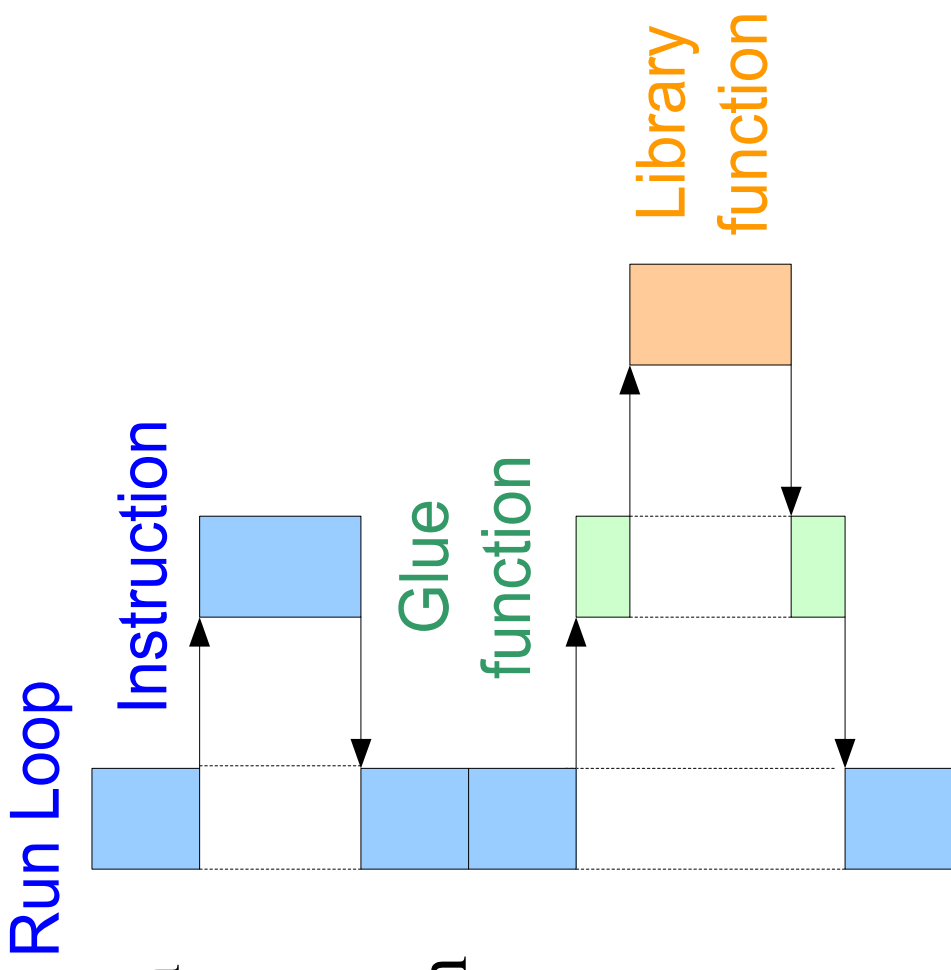
```
int reg[32]; // array of registers
int memory[BIG]; // memory of the VM
void run() {
    while (true) {
        Inst i = *pc++;
        int src1 = *(i.ptr1); // points to register!
        if (i.src1_in_memory)
            src1 = memory[src1]; // allow indirection
        i.action(src1, src2, dst);
    }
}
void add_int(int src1, int src2, int *dst) {
    *dst = src1 + src2;
}
```

Tricks

- Develop a sense of relative speeds:
opcode < if < switch << function call
(i.e. isub < jeq < jumptable <<< call)
- Pointers are faster than using array[index].
- Do as much work at load-time as possible, and as little at run-time as possible (e.g. static type-checking, point to registers not register indexes, Java doesn't need to check for stack overflow at run-time!)
- Beware: loop unrolling and inline macros don't always speed up code!

Glue Functions

- Instructions (built into the VM) are not enough to do all the work.
- We need a way to call additional libraries from our VM.



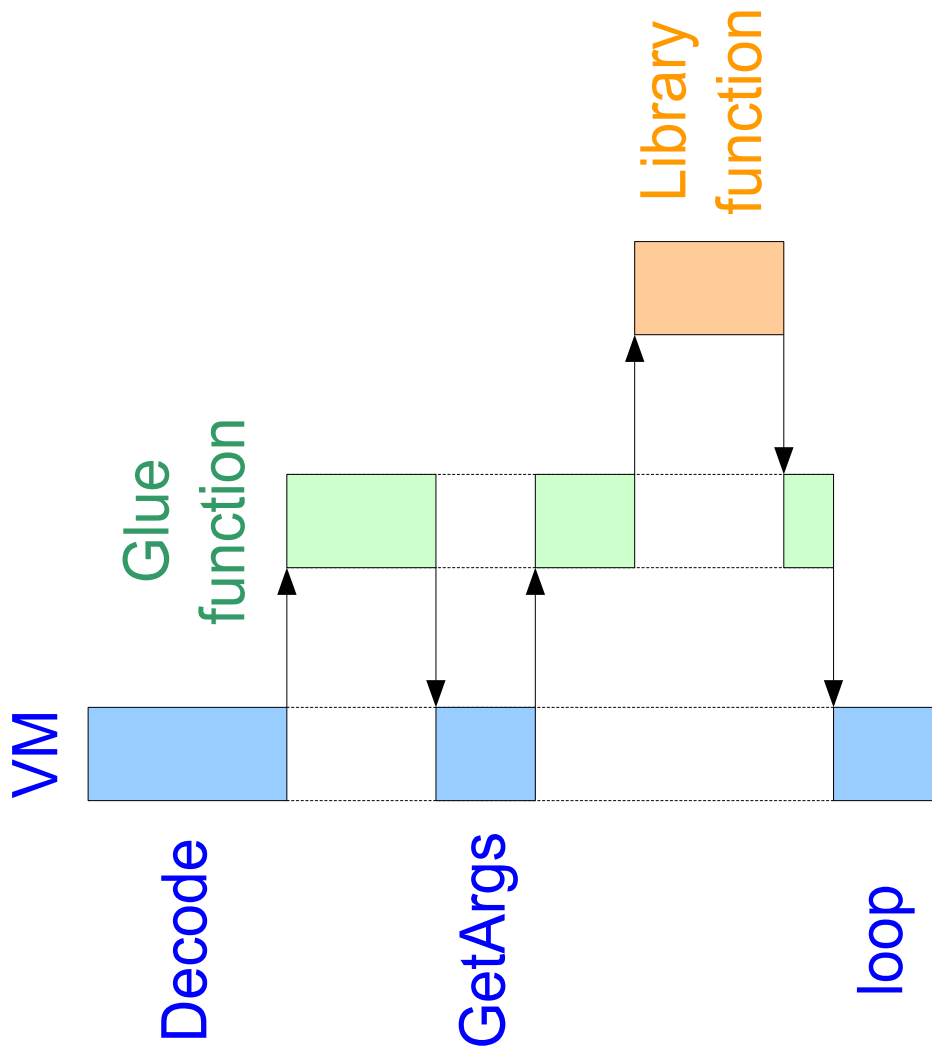
Python glue functions

```
static PyObject *
my_print(PyObject *self, PyObject *args)
{
    char *str;
    int retval;
    if (!PyArg_ParseTuple(args, "s", &str))
        return NULL;
    retval = printf("%s", str);
    return Py_BuildValue("i", retval);
}
```

ICI glue functions

```
static int
f_myfunc()
{
    long i;
    double f;
    if (ici_typecheck("if", &i, &f))
        return 1;
    printf("Got %ld, %lf.\n", i, f);
    return int_ret(i + 1);
}
```

Pulling data from the VM



Java glue functions

```
JNIEXPORT void JNICALL
Java_MyApplication_copyarray
(JNIEnv *env, jclass myclass,
 jintArray i1, jintArray i2, jint size)
{
    long *iarr = malloc(sizeof(long) * size);
    env->GetIntArrayRegion(i1, 0, size, iarr);
    env->SetIntArrayRegion(i2, 0, size, iarr);
    free(iarr);
}
```

But which is best?

- I want numbers! I want answers!
- There's only one way to get real answers:
- **Test!**

One test in a test suite

```
int main(int argc, char *argv[])
{
    long repeat;
    long r0, r4;

    scanf("%ld", &repeat);
    r0 = repeat;
    r4 = 7;
    while (0 < r0) {
        r4 = r4 / 2;
        r4 *= 13;
        r4 += repeat;
        r4 %= 11;
        r0 --;
    }
    printf("%ld", r4);
    printf(" was the result\n");
    return 0;
}
```

Integer instruction speed

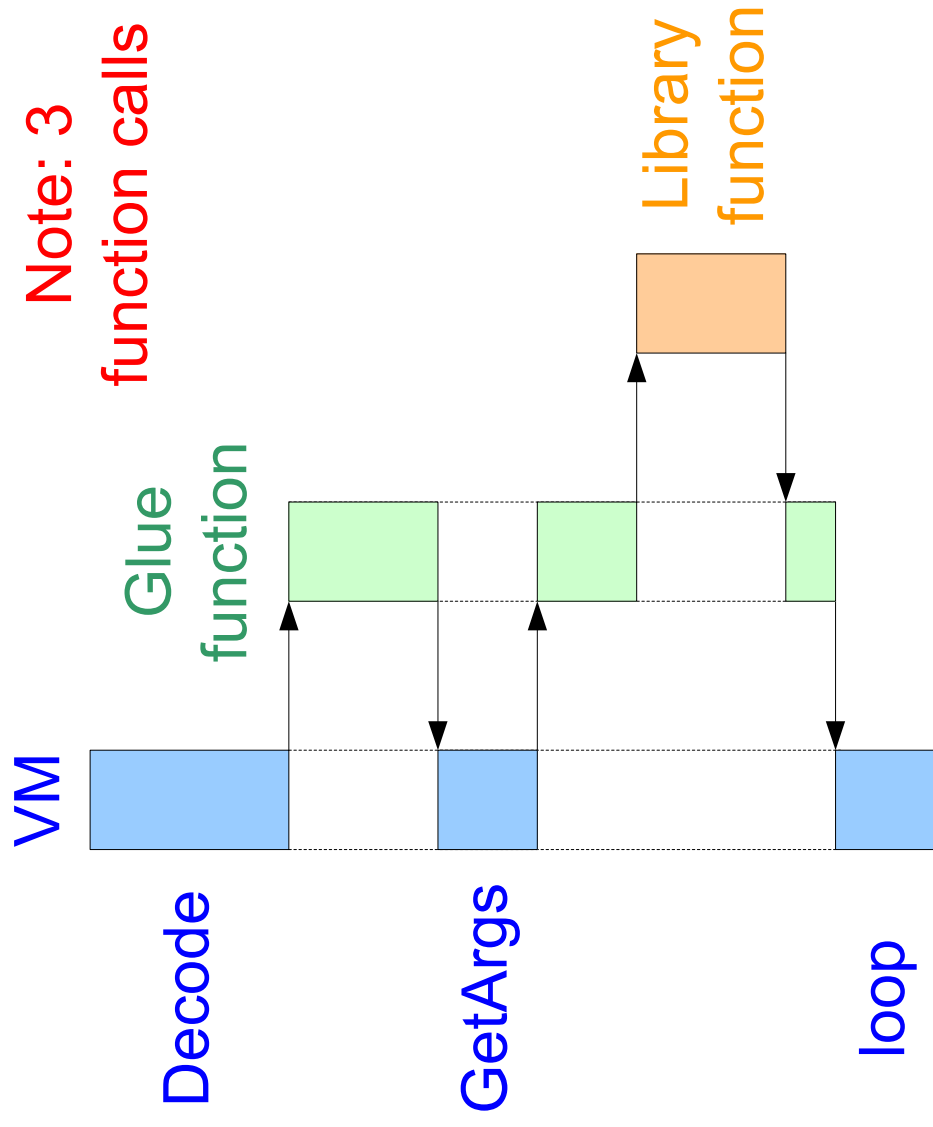
	2 million	20 million	
TECHNOLOGY	TIME	RAM	TIME
C (gcc -O2) :	0.04s	336K	0.45s
C (gcc) :	0.15s	336K	1.54s
Java 1.3.1:	0.57s	6204K	2.76s
LokiVM2002:	0.81s	400K	8.20s
Java no JIT:	0.91s	6668K	7.18s
LokiVM2000:	1.28s	416K	12.60s
AWK	2.72s	496K	27.10s
Lua 4.0:	4.58s	508K	(Wrong output!)
Perl 5.005:	4.70s	988K	46.43s
ICI 4.1.0:	5.65s	812K	56.45s
Python 2.1:	5.68s	1448K	55.93s
Python 1.5.2:	6.26s	1096K	62.44s

String instruction speed

1 million

TECHNOLOGY	TIME	RAM
C (factored) :	4.84s	292K (strlen outside)
LokiVM2002 :	5.73s	404K
Perl 5.005 :	7.61s	1100K
C (naïve) :	8.57s	292K (used gcc -O2)
LokiVM2000 :	8.83s	420K
AWK :	9.47s	484K
Python 2.1 :	11.54s	1456K
Python 1.5.2 :	13.54s	1096K
LokiVM1999 :	14.14s	404K
Java 1.3.1 :	15.51s	7936K (in 2 processes)
ICI 4.1.0 :	21.40s	792K
Lua 4.0 :	>12hrs	760K-12MB (!)

Pulling data from the VM



Tricks

- The 80/20 rule: “make the stuff you do 80% of the time faster, and don’t worry if the other 20% gets slower.”
- Weights: `switch <<< call`
- Corollary: Sometimes more code is faster than less code.

Switch statements

- Instead of just calling all instructions as functions:
`i.action(src1, src2, dst);`
- Do some instructions inside the execution loop:

```
switch(i.opcode) {  
    case INST_HALT:  
        return;  
    case INST_ADDI:  
        *dst = src1 + src2;  
        break;  
    case INST_JEQZ:  
        if (src1 == 0)  
            pc += src2 - 1;  
        break;  
    ...  
}
```

Glue code: therein lies the rub

- The problem is glue code is slow, hard to write, and no-one wants to do it.
- Maybe that's fine if glue code is part of the uncommon 20% which we don't care about, i.e. if 80% of the time our programs are doing built-in instructions like integer addition.
- Glue code is one case in the switch statement. And we just made it slower.

The glue code case

```
while (true) {
    ... // fetch and decode instruction
    switch(i.opcode) {
        case INST_ADDI:
            *dst = src1 + src2;
            break;
        ...
        case INST_GLUE:
            i.action(src1, src2, &dst);
            break;
        ...
    }
```

Tricks

- Observation: `void *` is versatile (more so than `int`).
- So, split the decoding between the execution loop and the glue code:
 - Use pointers inside the execution loop
 - Do type-checking per instruction
 - Let the glue code cast to the correct type

Attack of the void pointers

- Inside the execution loop:

```
void *src1, *src2, *dst;  
... // decode and run-time type-check  
i.action(src1, src2, dst);
```

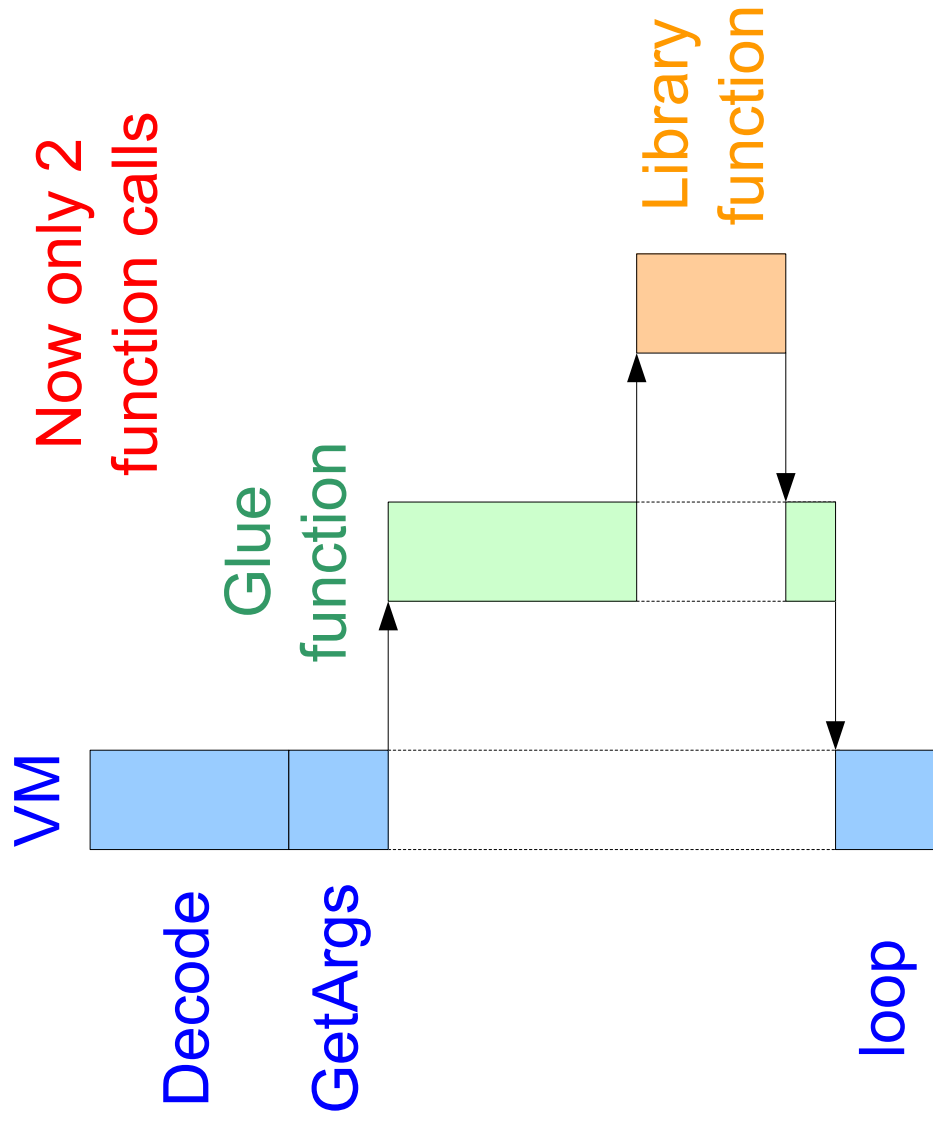
- The glue function:

```
void my_func(int *src1, int *src2,  
            int *dst)  
{  
    *dst = *src1 | (*src2 >> 8);  
}
```


Stocktaking

- Let's take stock. What have we achieved?
 - Decoding now happens in the execution loop.
 - Improves correctness, makes it easier to write glue code without fiddling with stack pointers or varargs.
 - Run-time type-checking is also in the run loop.
 - Thus, we don't need to call GetArgs (Yay! Faster!)
 - Built-in operations are also faster (80/20 rule).
- Problems remaining:
 - Inflexible three-parameter 'action' signature.

“GetArgs” now combined with execution loop



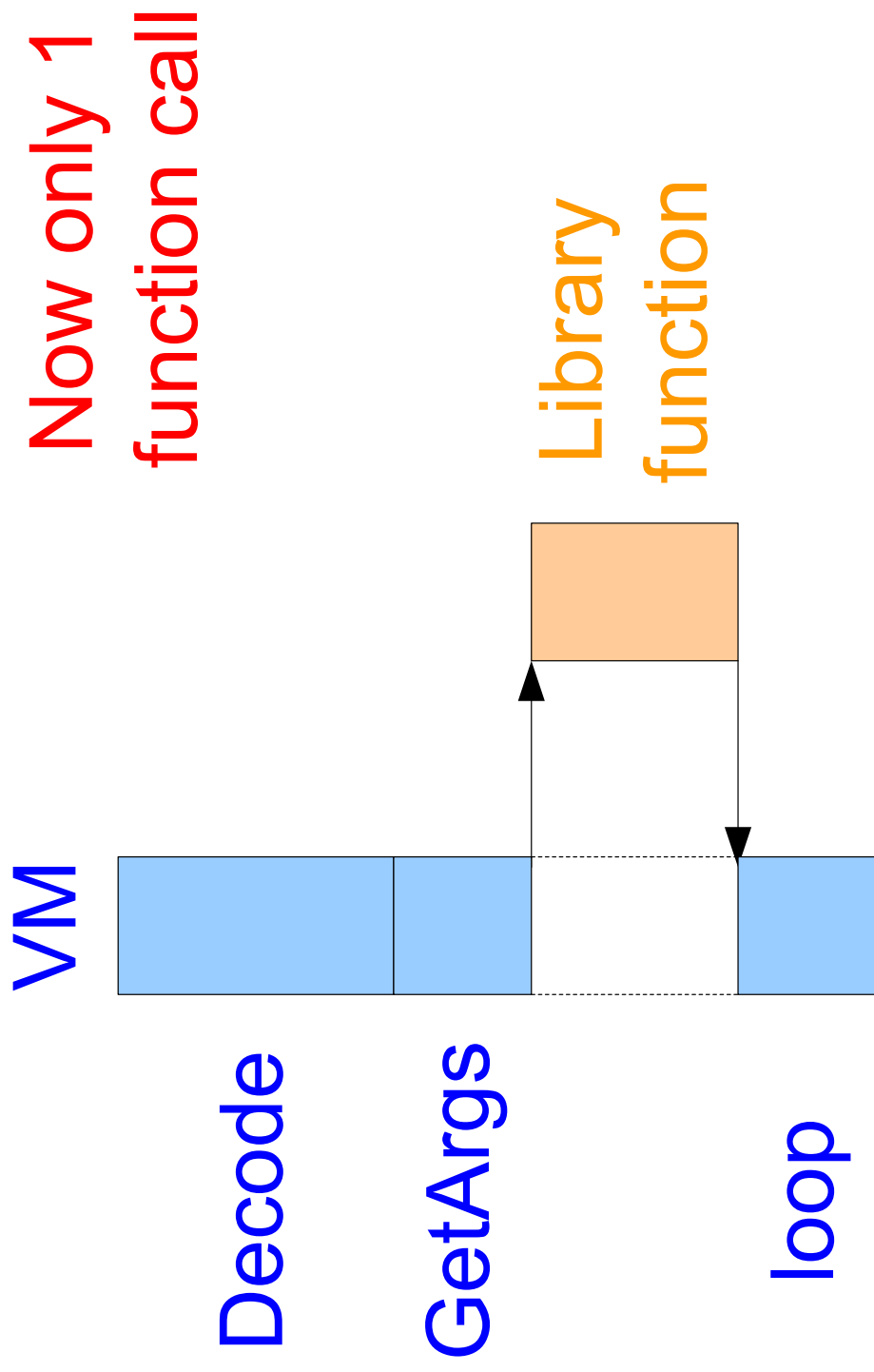
Tricks

- **If in doubt, apply the 80/20 rule again.**
(We already used this rule to speed up the built-in instructions. Can we use it to make common glue code faster, yet still make uncommon glue code possible?)
- **Observation: a jump table can become bigger without becoming slower.**
- **Corollary: “if you’ve already paid the toll, get your money’s worth.”**

Multiple action signatures

```
while (true) {
    ... // fetch and decode first 3 params
    switch(i.opcode) {
        ... // built-in instructions cases
        case INST_GLUE3:
            i.action(arg1, arg2, arg3);
            break;
        case INST_GLUE4:
            ... // decode 4th parameter
            i.action(arg1, arg2, arg3, arg4);
            break;
        ...
    }
}
```

Can we eliminate glue code *entirely*?



Just-In-Time compilers (JIT)

- A JIT converts virtual code at run-time into real CPU code. It's a compiler in the VM.
- Advantage: **speed!**
- JITs are an old idea: regular expressions have been compiled internally to CPU code since 1968. In fact Ken Thompson wrote a paper on just that idea (K. Thompson, *Regular Expression Search Algorithm*, Comm. Assoc. Comp. Mach., Vol. 11, 6, pp. 419--422, 1968).

A JIT implementation

- The simplest JIT implementation inputs a virtual program, compiles it internally, then jumps to the start of that code (after flushing the CPU's pipeline). On some platforms, it's just a matter of casting a memory block to a function pointer and calling it!
- Smarter techniques only compile single virtual functions, or virtual loops, and only when that code is commonly used (don't bother compiling single-use initialisation code).

Summary

- Function calls are modular, but switch statements are faster.
- Choose the trade-offs between speed and correctness.
- Sometimes tuning your code and thinking about data movements can produce radical improvements, even without using JITs/hardware/assembly language.
- Test and profile (it's the only way to be sure).