

Embedding Foreign Code

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Accelerate

```
dotp :: Acc (Vector Float) -> Acc (Vector Float) -> Acc (Scalar Float)
dotp xs ys = fold (+) 0 (zipWith (*) xs ys)
```

```
type Scalar e = Array Z e
type Vector e = Array (Z:.Int) e
type Matrix e = Array (Z:.Int:.Int) e
```

Skeletons

```
[cunit]
__global__ void map( $params:argIn, $params:argOut )
{
    const int shapeSize      = size(sh0ut);
    const int gridSize       = $exp:(gridSize dev);

    for (int ix = $exp:(threadIdx dev); ix < shapeSize; ix += gridSize)
    {
        $items:(dce x      .=. get ix)
        $items:(set0ut "ix" .=. f x)
    }
}
```

```
data DelayedAcc a where
  Delayed :: (Shape sh, Elt e)
    => Exp sh                                -- array extent
    -> Fun (sh -> e)                        -- generate element at index
    -> Fun (Int -> e)                        -- ...at linear index
    -> DelayedAcc (Array sh e)
```

```

[cunit]
__global__ void foldAll( $params:argIn, $params:argOut )
{ // omitted variable declarations
  if ( ix < shapeSize ) {
    $items:(y .=. get ix)

      for ( ix += gridSize; ix < shapeSize; ix += gridSize ) {
        $items:(x .=. get ix)
        $items:(y .=. combine x y)
      }
  }
  $items:(sdata "threadIdx.x" .=. y)
  __syncthreads();
  $stms:(treeReduce dev combine sdata)
  // first thread writes the result to memory
}
[]

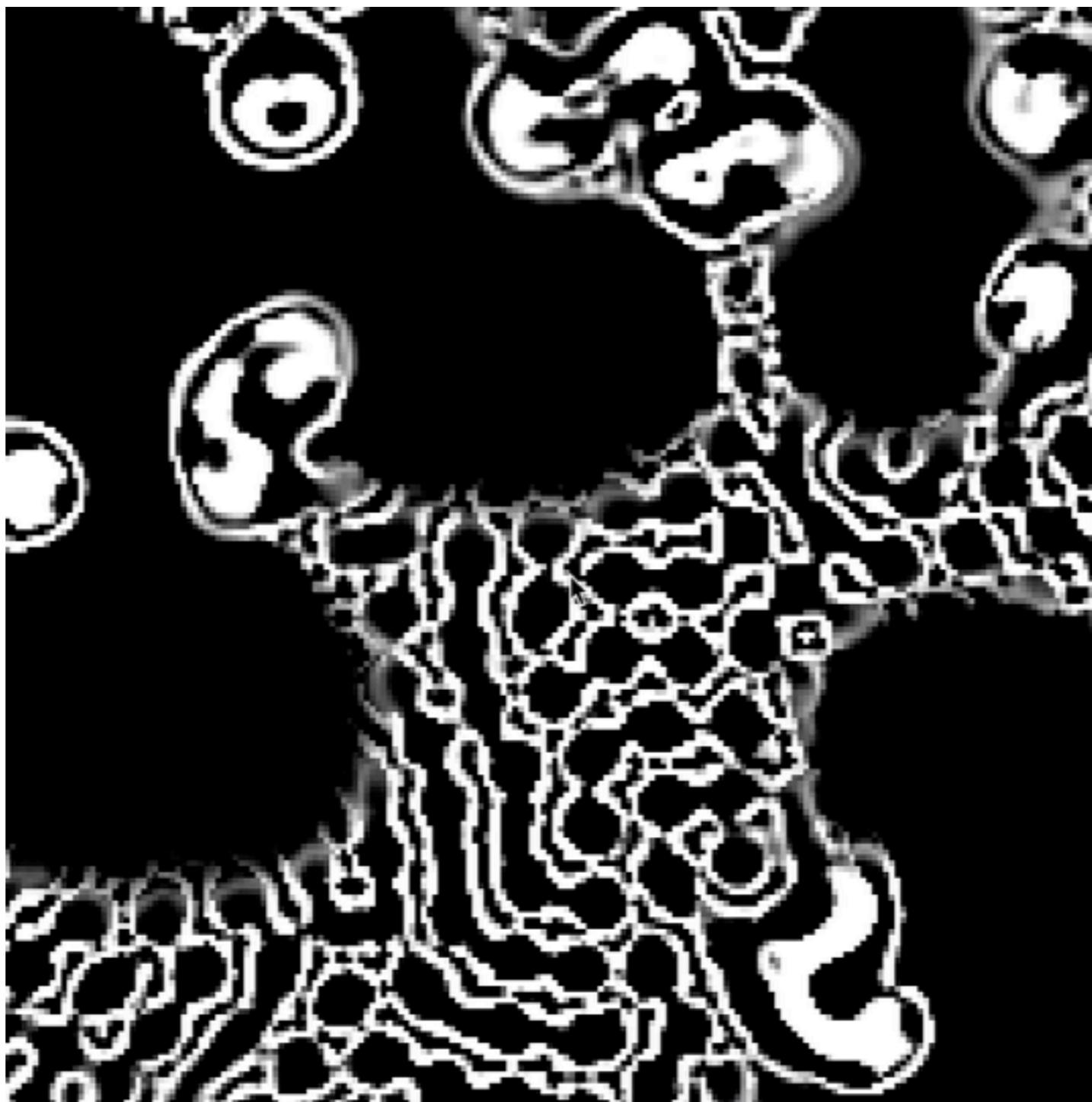
```

```

const Int64 v2 = ix;
const int v3 = toIndex(shIn0, shape(v2));
const int v4 = toIndex(shIn1, shape(v2));
float y0 = arrIn0_a0[v3] * arrIn1_a0[v4];

```

Foreign libraries



User's view

```
foreign import ccall "cublas_v2.h cublasSdot_v2" cublasSdot
    :: Handle
    -> Int                         -- Number of array elements
    -> DevicePtr Float -> Int      -- The two input arrays, and...
    -> DevicePtr Float -> Int      -- ...element stride
    -> DevicePtr Float              -- Result array
    -> IO ()
```

```
dotp_cublas :: Handle
    -> (Vector Float, Vector Float)
    -> IO (Scalar Float)
dotp_cublas handle (xs, ys) = do
    let n  = arraySize (arrayShape xs)          -- number of input elements
    result <- allocateArray Z                  -- allocate a new Scalar array
    ((),xptr) <- devicePtrsOfArray xs         -- get device memory pointers
    ((),yptr) <- devicePtrsOfArray ys
    ((),rptr) <- devicePtrsOfArray result
    liftIO $ cublasSdot handle n xptr 1 yptr 1 rptr
    return result
```

Internally

```
data Acc a where
  Map      :: (Elt a, Elt b, Shape sh)
            -> (Exp a -> Exp b)
            -> Acc (Array sh a)
            -> Acc (Array sh b)
  ...
  Aforeign :: (Arrays as, Arrays bs, Foreign f)
            => f as bs                                -- foreign function
            -> (Acc as -> Acc bs)                  -- fallback implementation
            -> Acc as                               -- input array
            -> Acc bs
```

```
class Typeable2 f => Foreign f where ...
```

```
data CUDAForeignAcc#(bs) = CUDAForeignAcc#(as, bs)
```

```
instance Foreign#(bs) CUDAForeignAcc#(bs)
```

Back to user

```
dotp' :: Acc (Vector Float) -> Acc (Vector Float) -> Acc (Scalar Float)
dotp' xs ys = Aforeign (CUDAForeignAcc (dotp_cublas handle))
                      (uncurry dotp)
                      (lift (xs, ys))
```

Accelerate as a C library



User's view

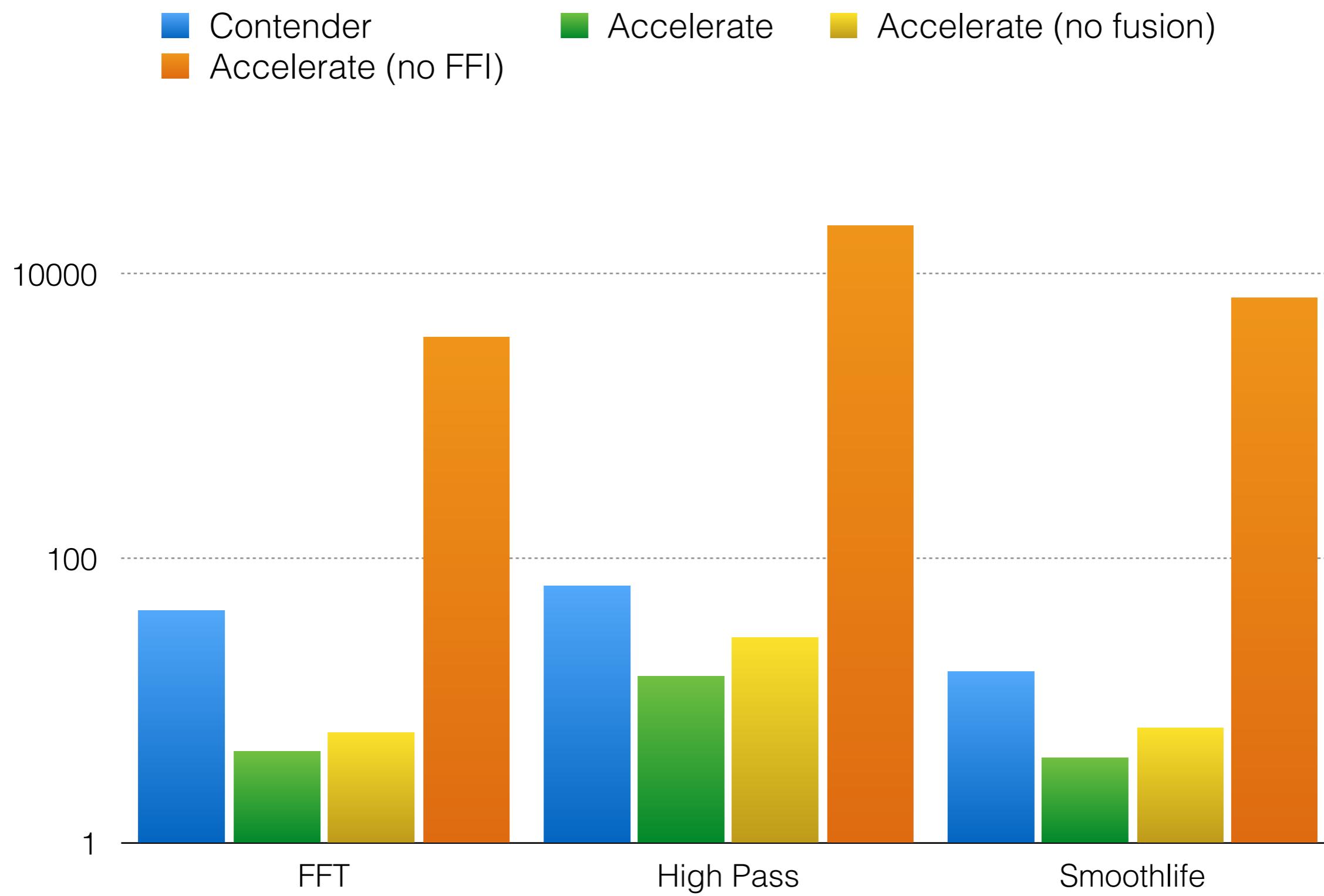
DotP.hs:

```
dotp :: Acc (Vector Float, Vector Float) -> Acc (Scalar Float)
dotp = uncurry $ \xs ys -> fold (+) 0 (zipWith (*) xs ys)

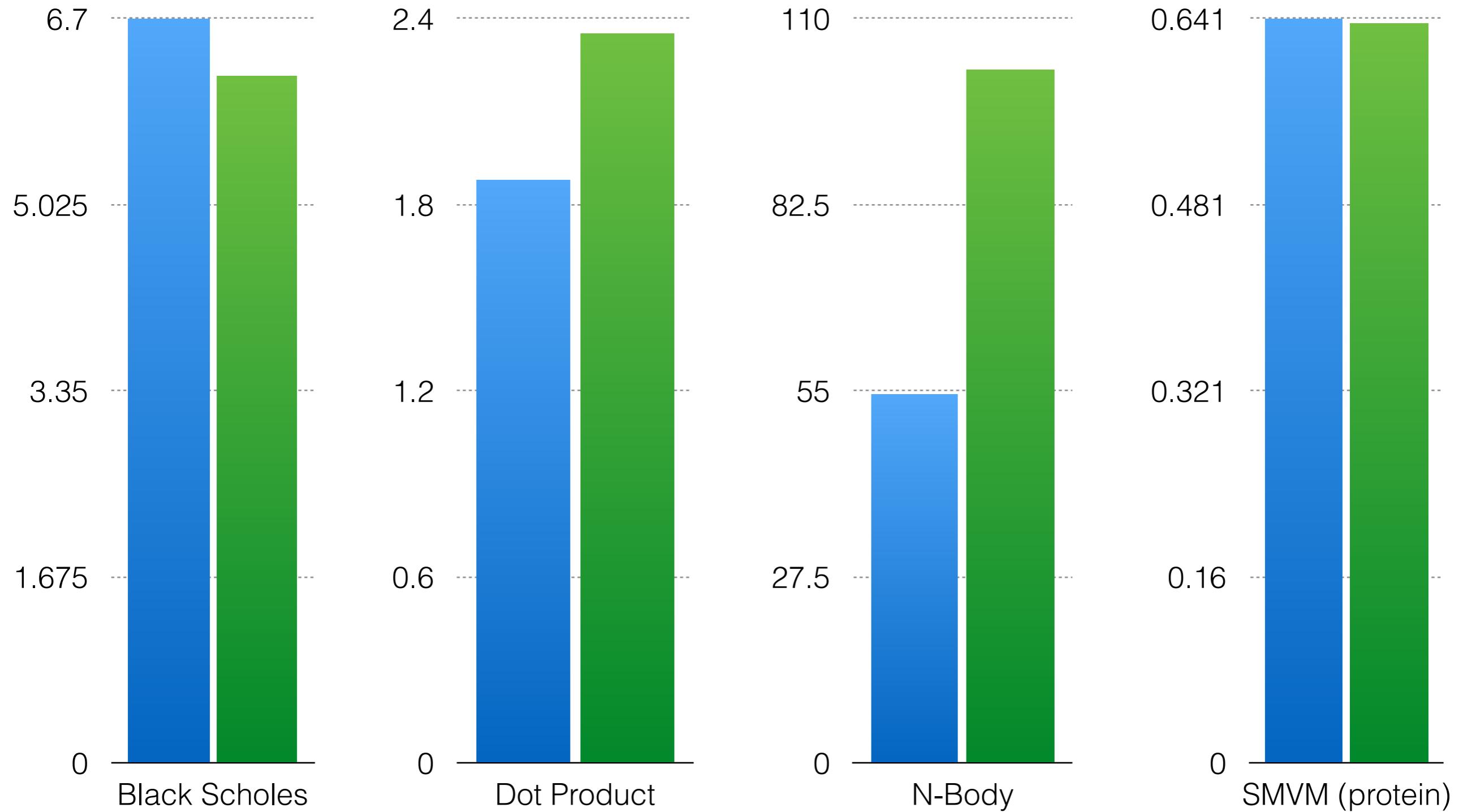
exportAfun 'dotp "dotp_compile"
```

DotP_stub.h:

```
#include "HsFFI.h"
extern AccProgram dotp_compile(AccContext a1);
```

CUDA
Accelerate



Questions?