



Fritz Henglein; Ralf Hinze

DIKU, University of Copenhagen; DCS, University of Oxford

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Sorting and searching

- Two principal approaches:
 - Comparison-based methods (e.g. Quicksort; red-black trees)
 - Distributive methods (e.g. radix sort; tries, hashing)
- Generic sorting and searching?
 - Parameter: User-defined sort order



Comparison-based sorting: Quicksort



Generic comparison-based sorting: HOF abstraction



Generic comparison-based sorting: Discussion

- Methods are easily made generic: turn the comparison function into a parameter ("black-box" approach).
- But:
- User-specified function may or may not be a comparison function.
- Both sorting and searching are subject to lower bounds:
 - sorting requires $\Omega(n \log n)$ comparisons, and
 - searching for a key requires $\Omega(\log n)$ comparisons,
- where n is the number of keys in the input.
- Often, comparison is not a constant-time operation

Idea: DSI for orders



Order Representations: Definition

• An element of Order K represents an order over the type K:

```
data Order :: * -> where
   OUnit ::Order()
   OSum :: Order k1 -> Order k2 -> Order (k1 + k2)
   OProd :: Order k1 -> Order k2 -> Order (k1, k2)
   OMap :: (k1 -> k2) -> (Order k2 -> Order k1)
   OChar :: Order Char -- 7 bit ASCIIdata
```



Order Representations: Examples

Reverse lexicographic order:

```
rprod :: Order k1 -> Order k2 -> Order (k1, k2)
rprod o1 o2 = OMap (fn (a, b) -> (b, a)) (OProd o2 o1)
```

• Ordering recursive types, eg strings:

```
ostring :: Order String
ostring = OMap out (OSum OUnit (OProd OChar ostring)))
```

data String = [] | (Char : String)



Generic comparison function

qsort (lte ostring)

• Interprets an order representation as comparison function:

```
lte :: Order k \rightarrow (k \rightarrow k \rightarrow Bool)
 lte OUnit a b = True
 lte (OSum o1 o2) a b =
     case (a, b) of
           (Inl a1, Inl a2 ) -> lte o1 a1 a2
           (Inl _, Inr _ ) -> True
           (Inr _, Inl _ ) -> False
           (Inr b1, Inr b2 ) -> lte o2 b1 b2
 lte (OProd o1 o2) a b =
     lte o1 (fst a) (fst b) &&
      (lte o1 (fst b) (fst a) ==> lte o2 (snd a) (snd b))
 lte (OMap g o) a b = lte o (g a) (g b)
 lte (OChar) a b = a <= b
Sorting lists of words:
```

Distributive sorting & searching: Idea

- Employ the structure of order representations *directly*.
- A hierarchy of operations:

```
sort :: Order k -> List (k,v) -> List v
discr :: Order k -> List (k,v) -> List (List v)
trie :: Order k -> List (k,v) -> Trie k (List v)
```

• We separate keys from *satellite data*, i.e. associated values.



Distributive Sorting & Searching: Examples

• The keys are discarded:

```
sort ostring [("ab",1), ("ba",2), ("abc",3), ("ba",4)]
\Rightarrow [1.3,2.4]
Note: sort is stable.
```

Returning the keys (sorting as permutation):

```
sort ostring (map (fn a -> (a, a)) ["ab", "ba", "abc", "ba"])
⇒ ["ab", "abc", "ba", "ba"]
```

Grouping values with equivalent keys:

```
discr ostring [("ab",1), ("ba",2), ("abc",3), ("ba",4)]
```

```
\Rightarrow \lceil \lceil 1 \rceil, \lceil 3 \rceil, \lceil 2, 4 \rceil \rceil
```

Distributive searching:

```
let dict =
    trie ostring [("ab",1), ("ba",2), ("abc",3), ("ba",4)]
in lookup dict "ba"
```

$$\implies$$
 Just [2,4]



Generic distributive sorting

sort o takes list of key-value pairs, returns values in non-decreasing order of their associated keys.

```
sort :: Order k -> List (k,v) -> List v
sort o
sort OUnit
            rel = map (fn (k,v) \rightarrow v) rel
sort (OSum o1 o2) rel =
  sort o1 (filter froml rel) ++ sort o2 (filter fromr rel)
sort (OProd o1 o2) rel =
  sort o1 (sort o2 (map curryr rel))
sort (OMap g o) rel =
  sort o (map (f * id) rel)
sort (OChar) rel = bucketsort rel
```

Let us look at some clauses.



Distributive sorting: Discussion

- Each component of each key is touched *exactly* once.
 - Ignoring OMap.
- The running time is *linear* in the *total size* of the keys.
- sort generalizes least-significant-digit (LSD) radix sort to user-definable orders on arbitrary data types.
- sort uses o as a control structure to reduce a sorting problem to basic sorting on finite domains (bootstrapping).
 - Practical performance determined by sorting small integers.



Distributive sorting: Properties

- Naturality, sort o commutes with map:
 - map f . sort o = sort o . map (id * f)
- Strong naturality, sort o commutes with filtering:
 filter p . sort o = sort o . filter (id * p)
- Sorting singletons
 - sort o [(k, v)] = [v]
- Sorting pairs: sort o [(a,v), (b,w)] = [v,w] ←⇒ lte o a b = True

Theorem: Strong naturality + sorting singletons + sorting pairs \implies stable sort.



Generic Tries: Definition

 An element of Trie K V represents a finite map from K to V. Introduce map constructors:

```
data Trie k v where
```

```
TEmpty :: Trie k v -- empty map
```

TUnit :: $v \rightarrow$ Trie () $v \rightarrow$ singleton map

TSum :: Trie k1 -> Trie k2 v -> Trie (k1 + k2) v TProd :: Trie k1 (Trie k2 v) -> Trie (k1, k2) v

TMap :: (k1 -> k2) -> Trie k2 v -> Trie k1 v

TChar :: Char.Map v -> Trie Char v

• The first type argument is an *index*, the second a *parameter*.



Building tries in bulk

```
build :: Order k -> List (k, v) -> Trie k (List v)
build o
                  [] = TEmpty
build (OSum o1 o2) rel = TSum (build o1 (filter from1 rel))
                             (build o2 (filter fromr rel))
build (\OmegaProd o1 o2) rel =
     TProd (fmap (build o2) (build o1 (map curryl rel)))
build (OMap g o) rel = TMap g (build o (map (g * id) rel))
build (OChar) rel = TChar (Char.build rel)
where
curryl ((k1, k2), v) = (k1, (k2, v))
and
fmap :: (v -> w) -> Trie k v -> Trie k w
is morphism mapping component of functor Trie k
```

Building tries in bulk: Complexity

trie and lookup are asymptotically optimal:

- trie builds a trie in time *linear* in the total size of the keys in the input.
- lookup :: Trie k v -> k -> Maybe v returns its result in time linear in the size of the key input (independent of the trie input)
 - Better yet: In the minimum distinguishing prefix of the key in the trie.
- (Ignoring OMap)
- Better than one-at-a-time insertion into trie.



Generic Tries: Properties

• Tries are based on the laws of exponentials (Trie K V $\cong V^K$):

$$V^{1} \cong V$$
 $V^{K_{1}+K_{2}} \cong V^{K_{1}} \times V^{K_{2}}$ $V^{K_{1}\times K_{2}} \cong (V^{K_{2}})^{K_{1}}$

Correctness:

```
discr o = flatten . trie o
sort o = concat . discr o
where flatten :: Trie k v -> List v flattens a trie into
a list by homomorphically interpreting trie constructors as list
```

operations.

Proofs use strong naturality properties of discr and sort



Benchmark: Searching the Bible

Preparatory steps (we use Project Gutenberg's The Bible):
 bible <- readFile "pg30.txt"

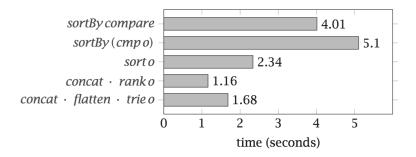
let rel = zip (words bible) [0 ..]
let concordance = build ostring rel

- Where is "God"?
 lookup concordance "God"
 ⇒ Just [467,496,506,518,527,536,559,583,610,...
- How frequent is "God"?
 fmap length (lookup concordance "God")
 ⇒ Just 2229
- And the "devil"?
 fmap length (lookup concordance "devil")
 ⇒ Just 23



Benchmark: Performance

Sorting the words of Project Gutenberg's The Bible (5218802 characters, 824337 words).





Summary

- Generic distributive sorting and searching
- Orders are represented syntactically
 - Many sort orders per type, not just standard order
- The separation of keys and values is essential:

```
sort :: Order k -> List (k, v) -> List v
discr :: Order k -> List (k, v) -> List (List v)
build :: Order k -> List (k, v) -> Trie k (List v)
```

- Correctness via strong naturality
- Keys are used affinely (used at most once) ⇒ linear time complexity
- Unoptimized Haskell implementation with surprisingly good performance



Related Work

- Cai, J., Paige, R.: Using multiset discrimination to solve language processing problems without hashing. Theoretical Computer Science 145(1-2) (July 1995) 189–228.
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- Connelly, R.H., Morris, F.L.: A generalization of the trie data structure. Mathematical Structures in Computer Science 5(3) (September 1995) 381–418.
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